

# Scoring Bayesian Networks of Mixed Variables

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# Learning Bayesian Networks (BNs)

- BNs constitute a widely used graphical framework for representing probabilistic relationships
- Many application in Bayesian Inference and Causal Discovery
- Learning structure is crucial
  - Limited work has been done in the presence of both discrete and continuous variables

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Goal: Provide scalable solutions for learning BNs in the presence of both discrete and continuous variables

# Outline

- Bayesian Information Criterion (BIC)
- Mixed Variable Polynomial (MVP) score
- Conditional Gaussian (CG) score
- Adaptations
- Simulations and empirical results

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Scores a BN as the sum over all BIC calculations for each node given its parents



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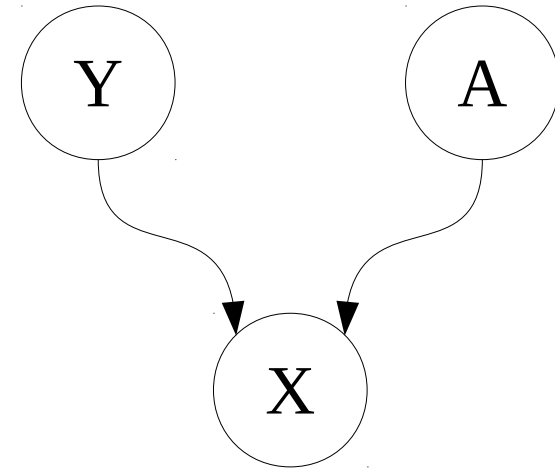
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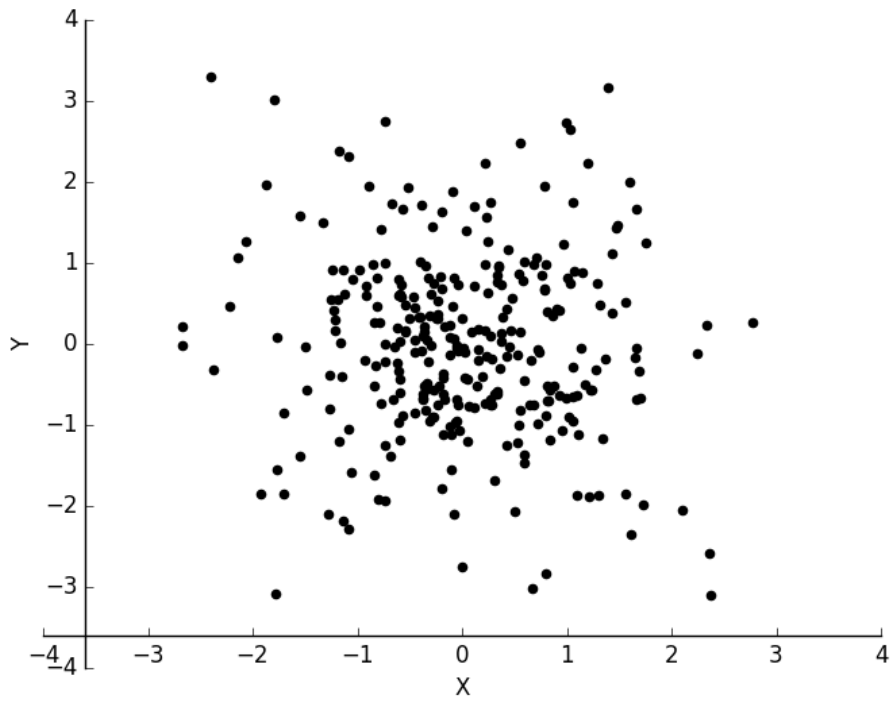
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- Score continuous child using BIC

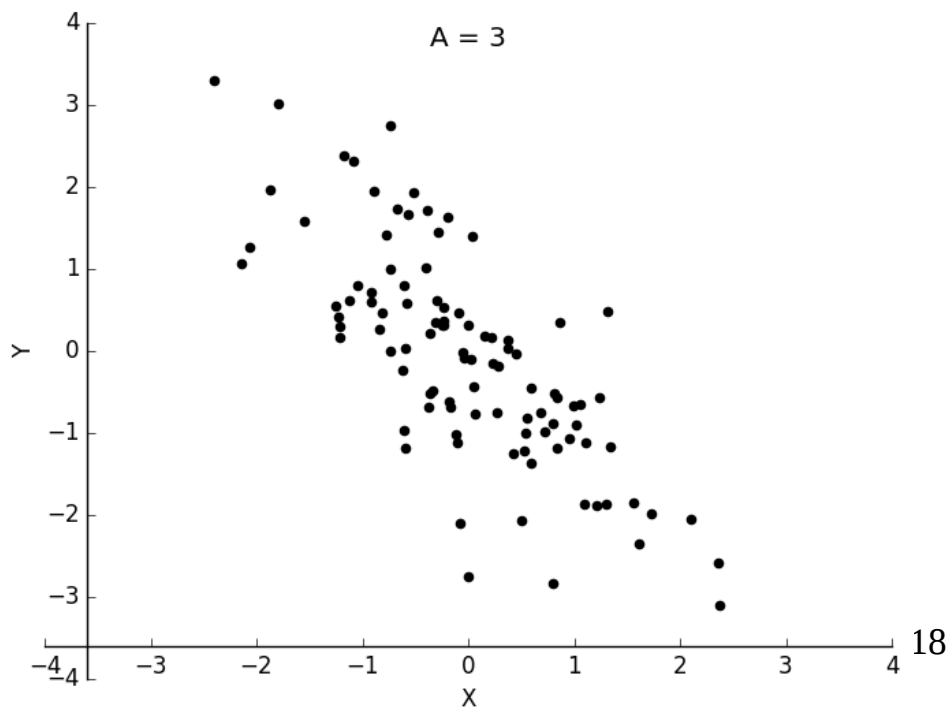
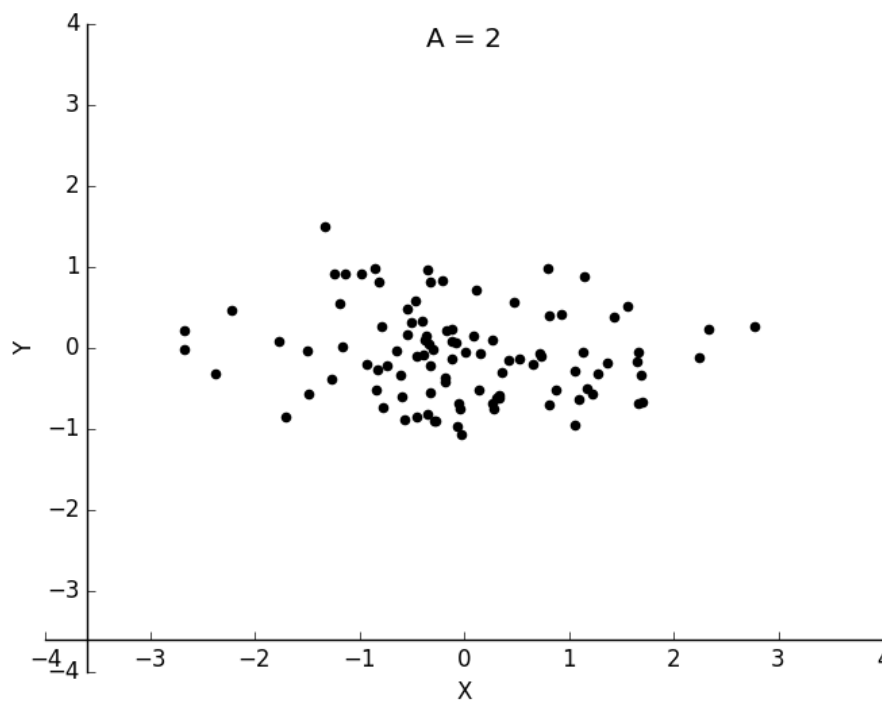
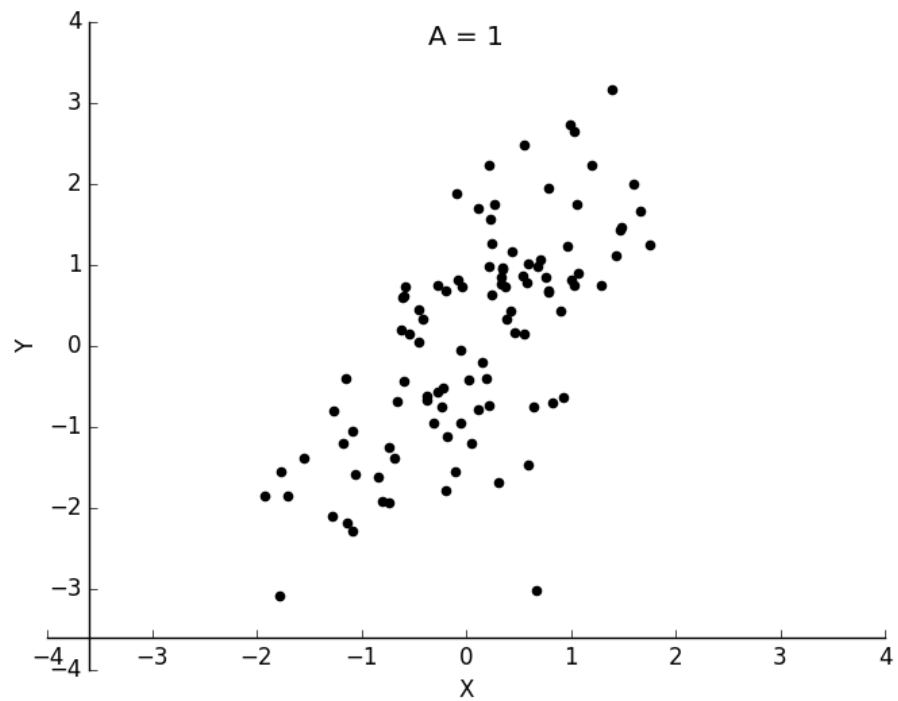
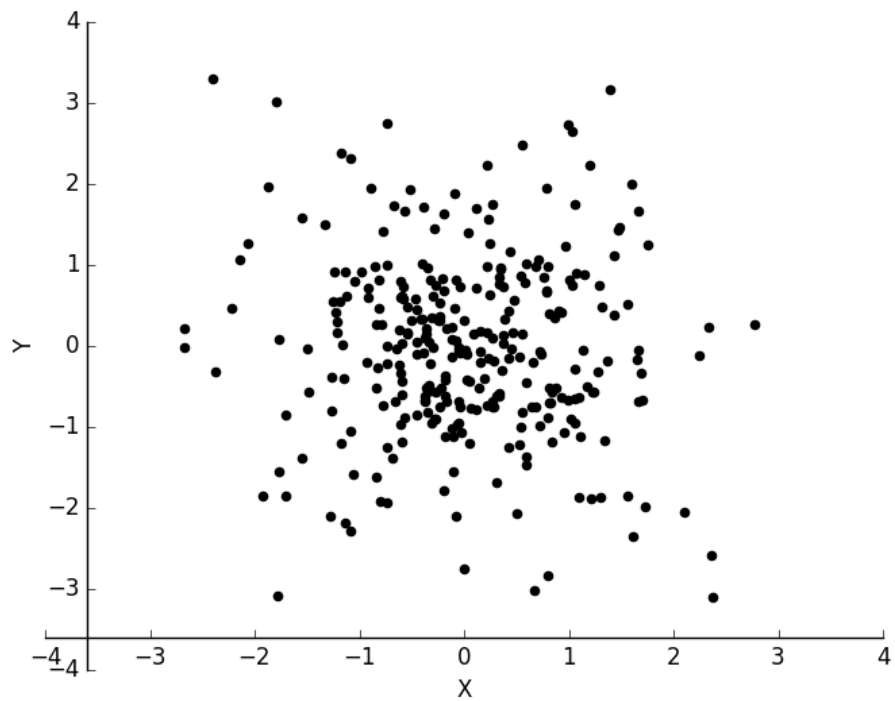
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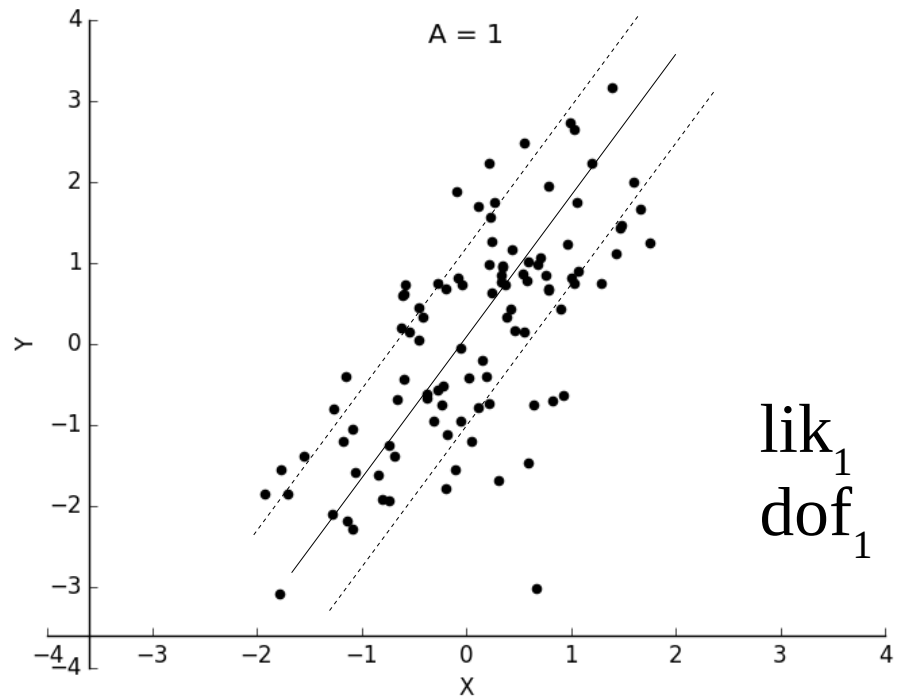
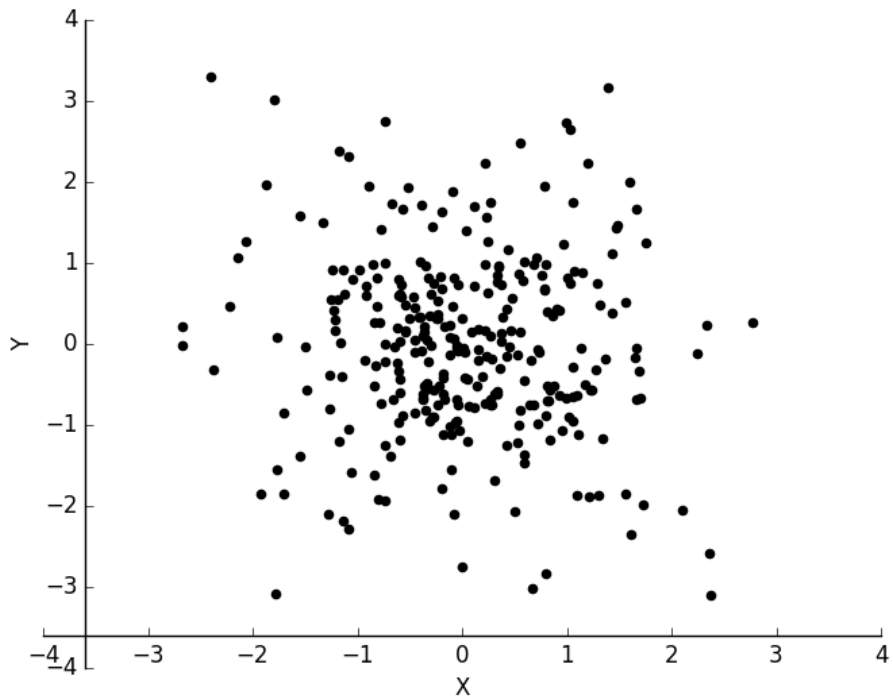
- Let  $X, Y$  be continuous
- Let  $A$  be discrete ( $|A| = 3$ )
- Want:  $\text{lik}_{X|Y,A}$ ,  $\text{dof}_{X|Y,A}$



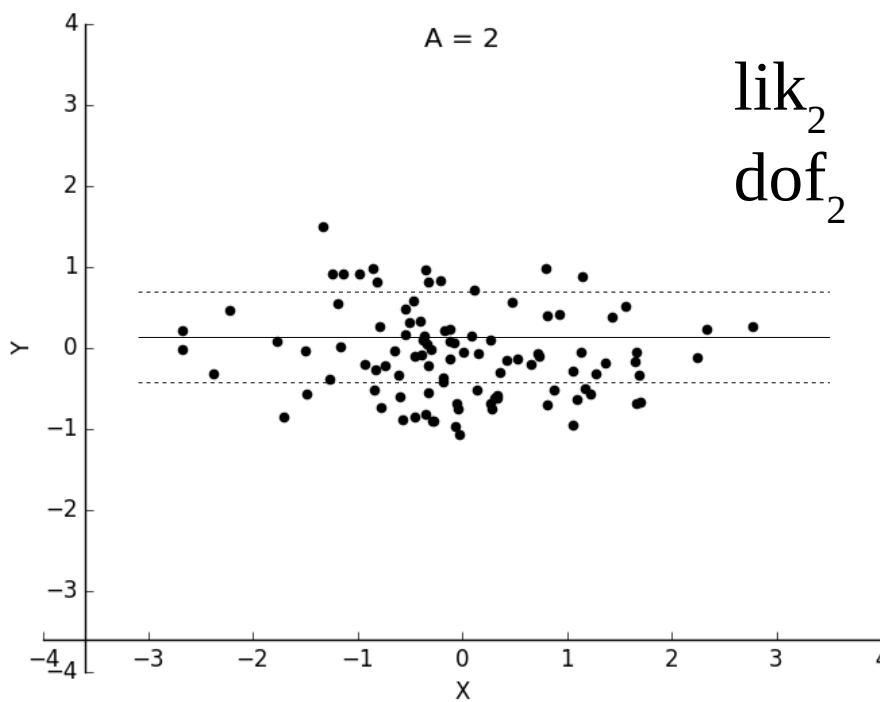




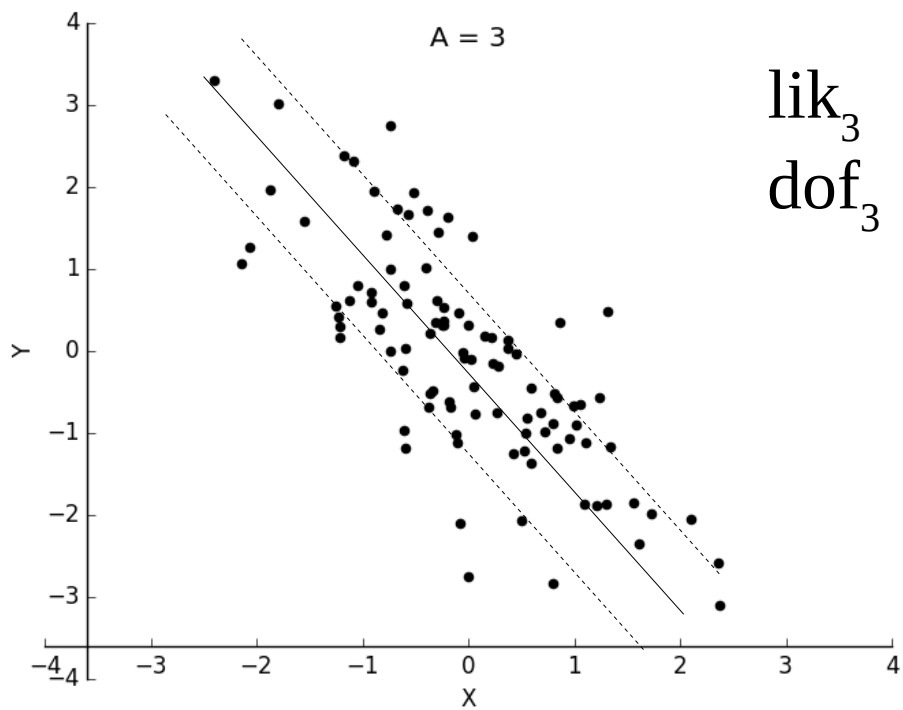




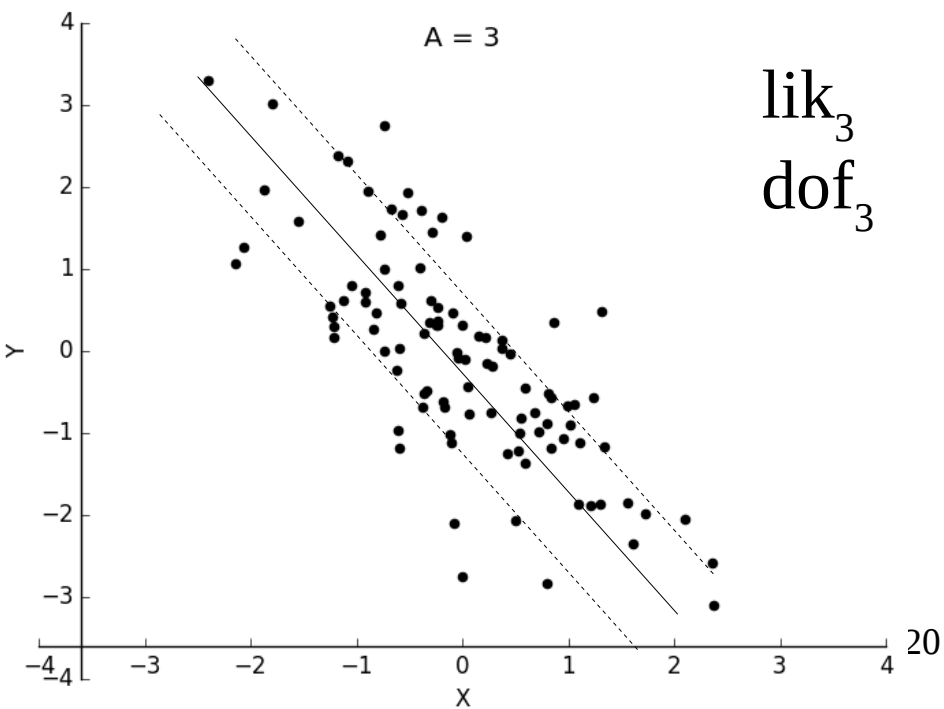
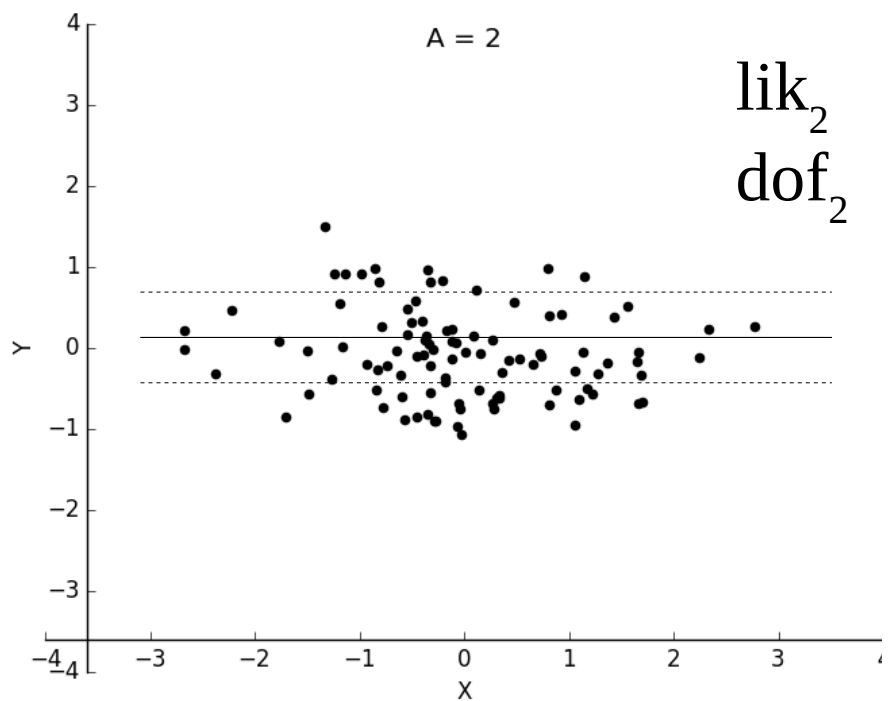
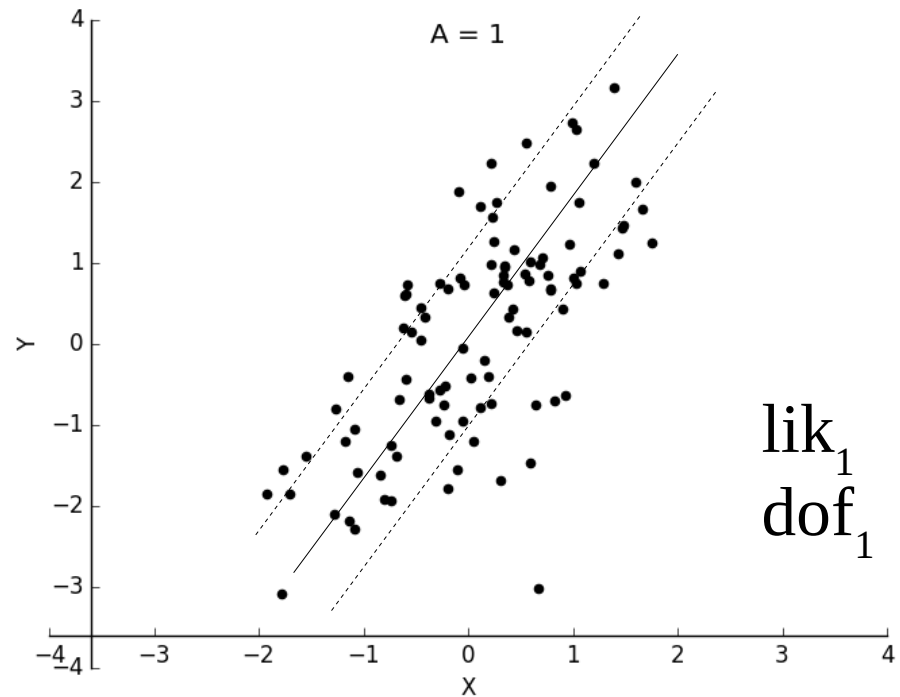
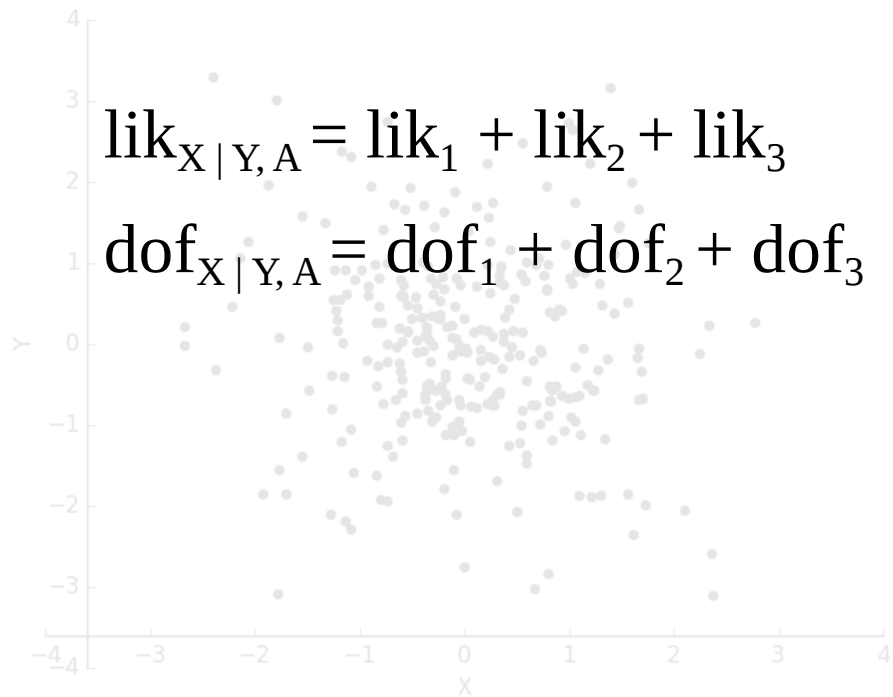
lik<sub>1</sub>  
dof<sub>1</sub>

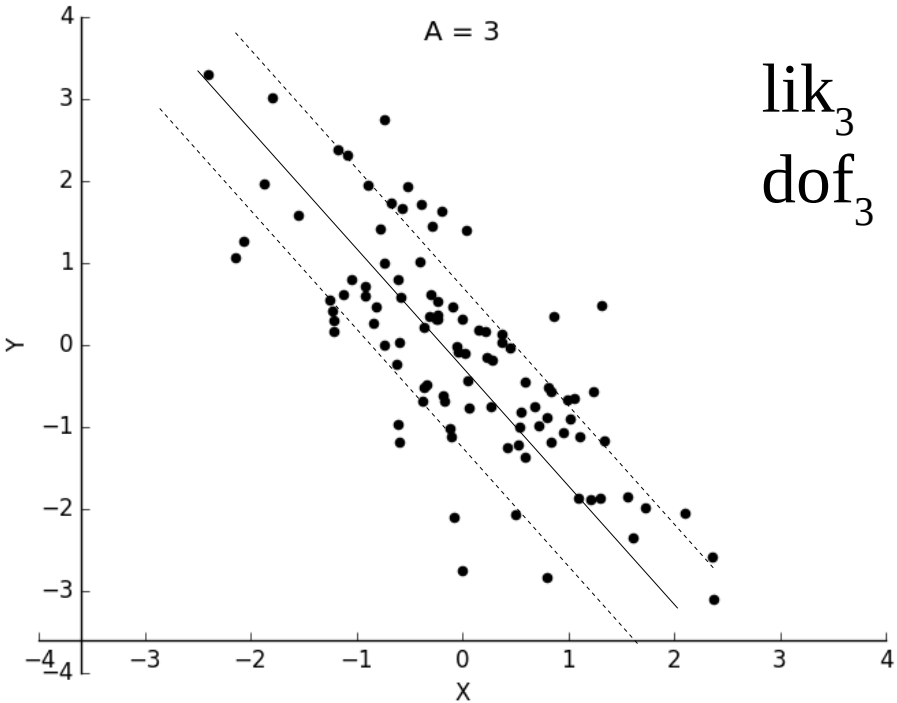
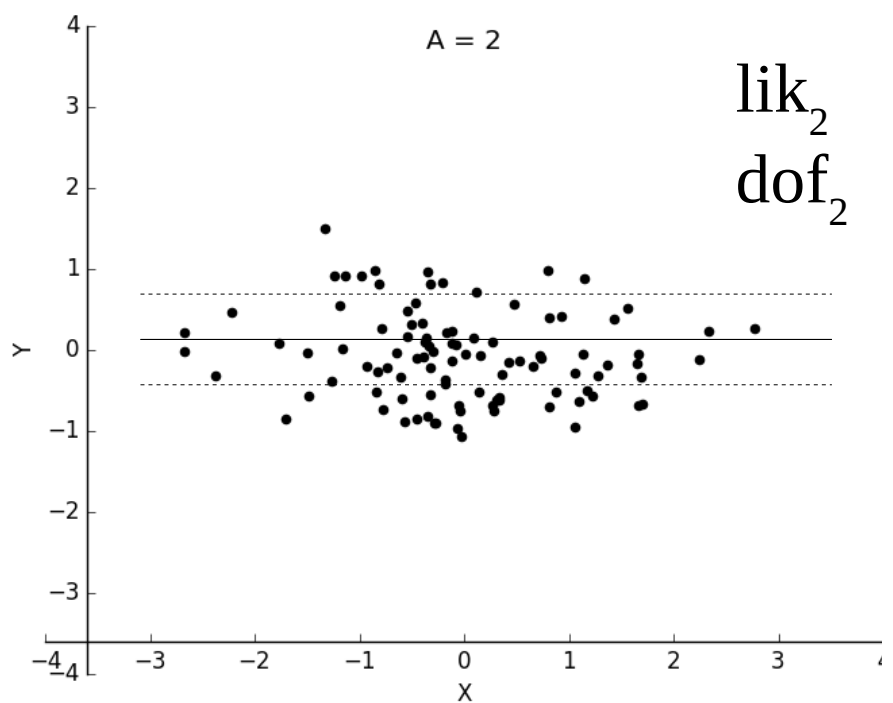
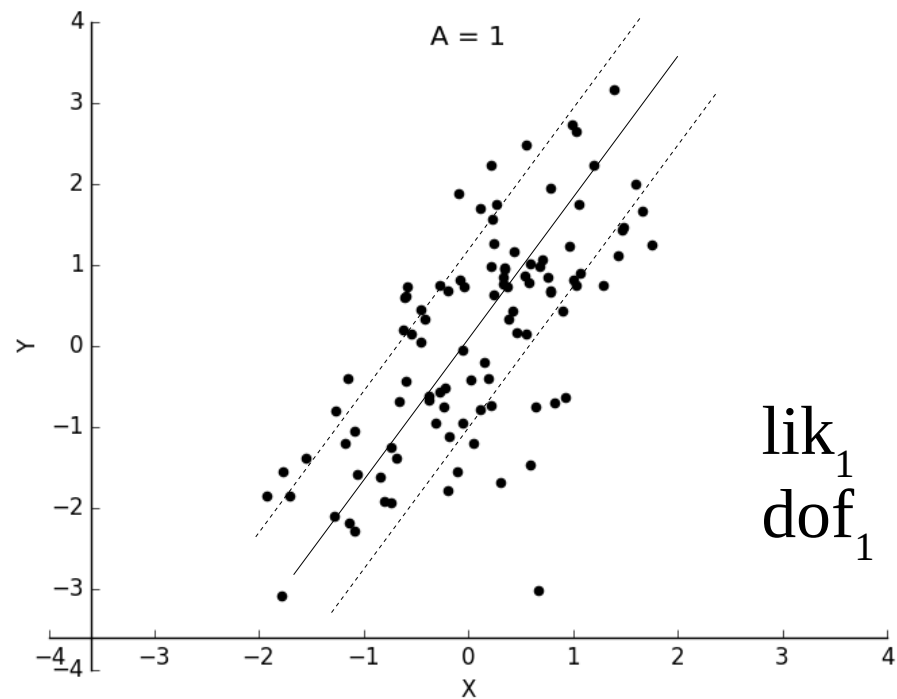
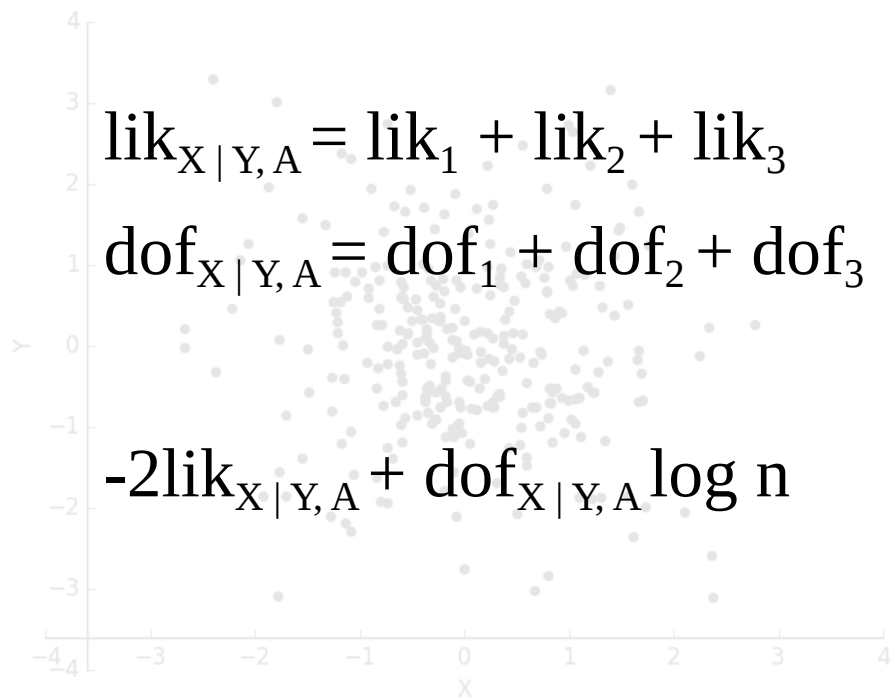


lik<sub>2</sub>  
dof<sub>2</sub>



lik<sub>3</sub>  
dof<sub>3</sub>





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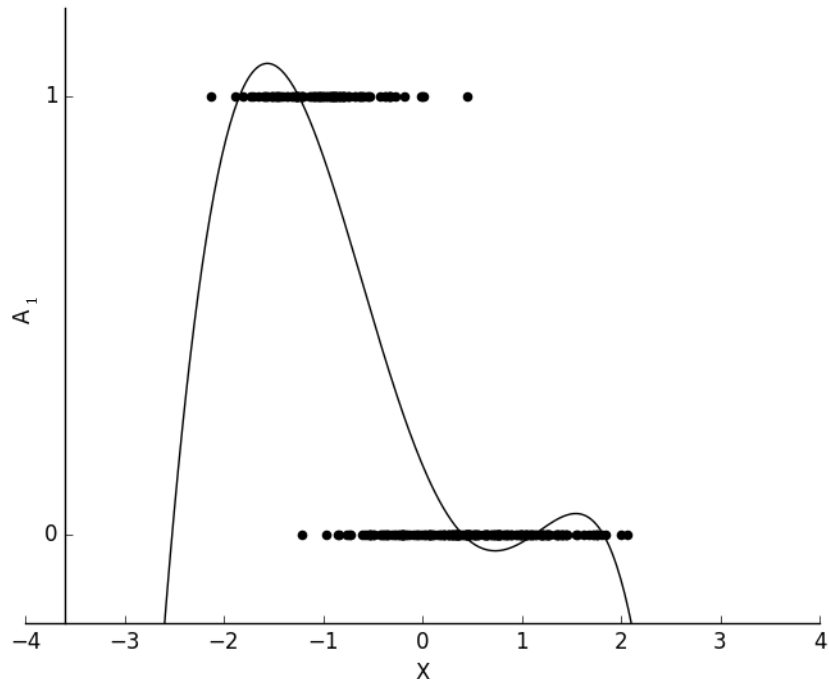
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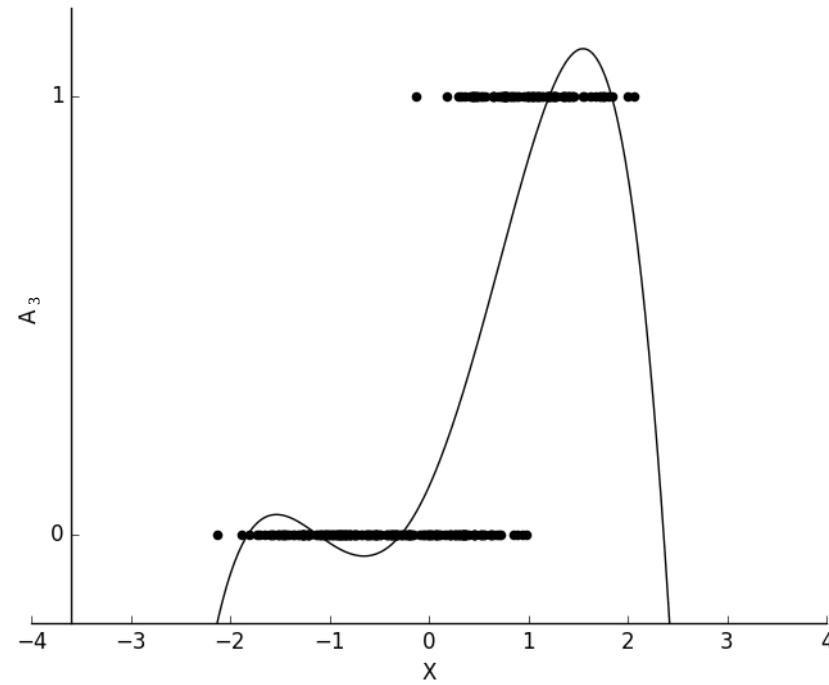
- Let  $X$  be continuous
- Let  $A$  be discrete ( $|A| = 3$ )
- Want:  $\text{lik}_{A|X}$ ,  $\text{dof}_{A|X}$



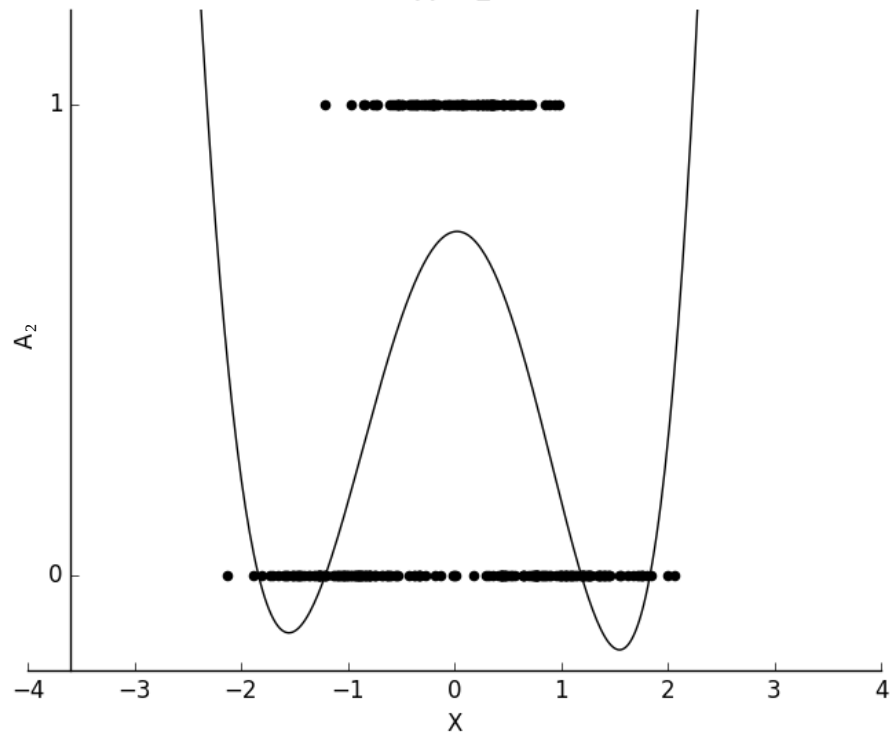
A = 1

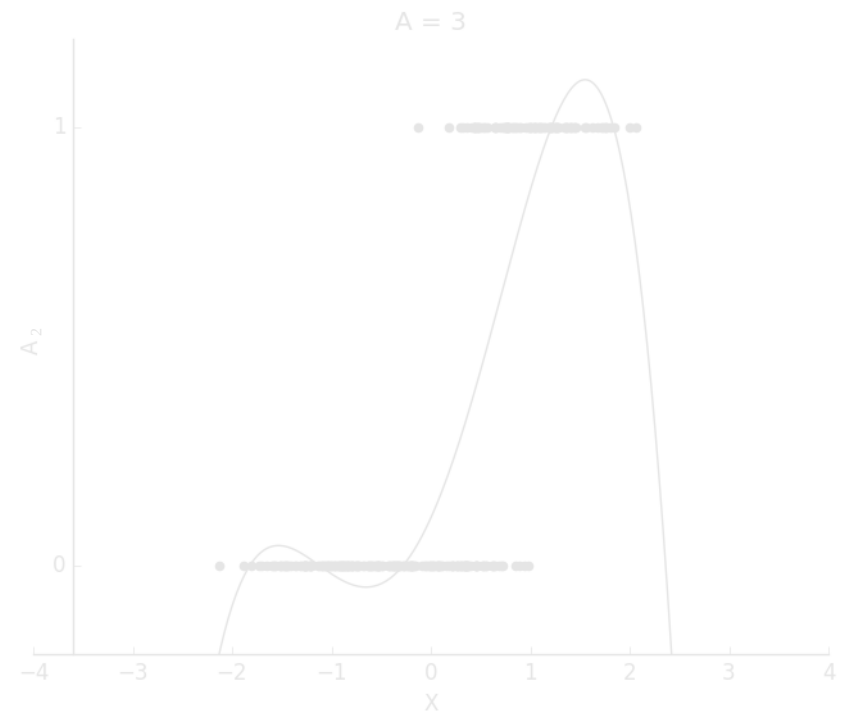
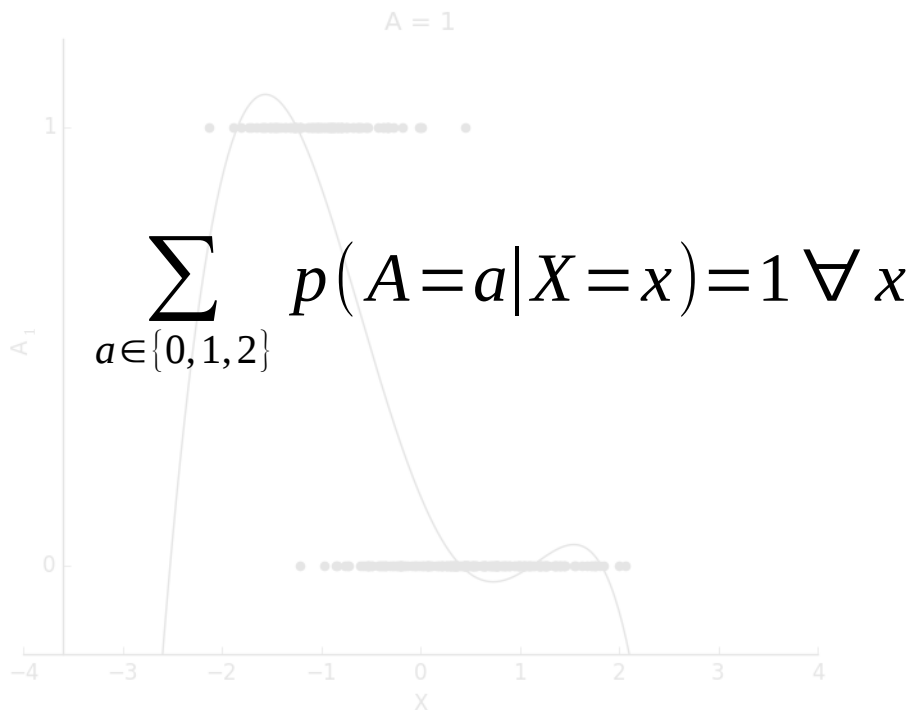


A = 3

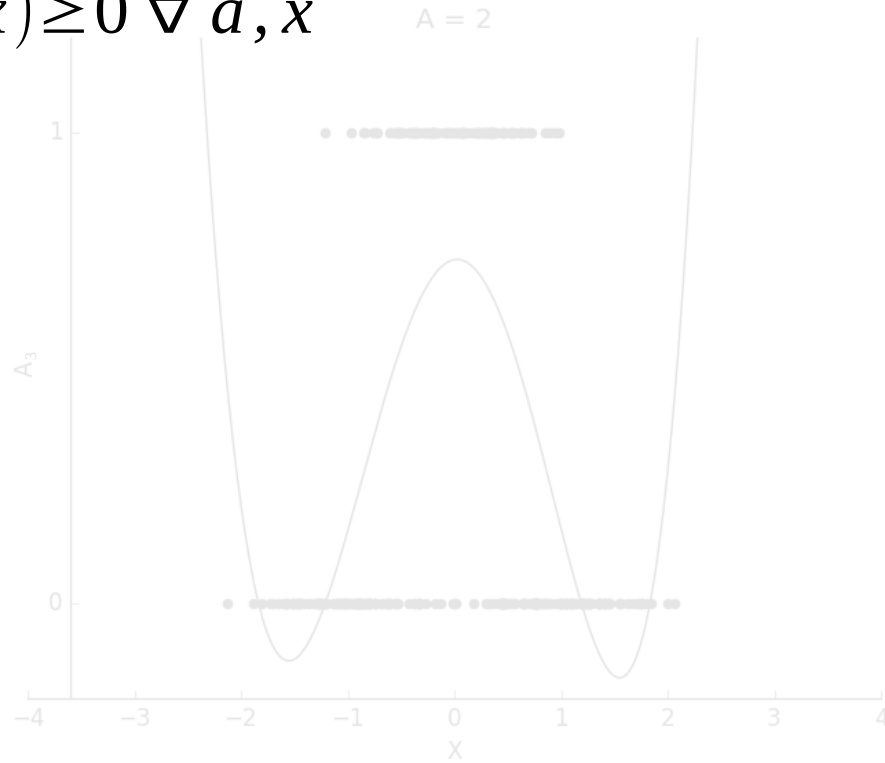


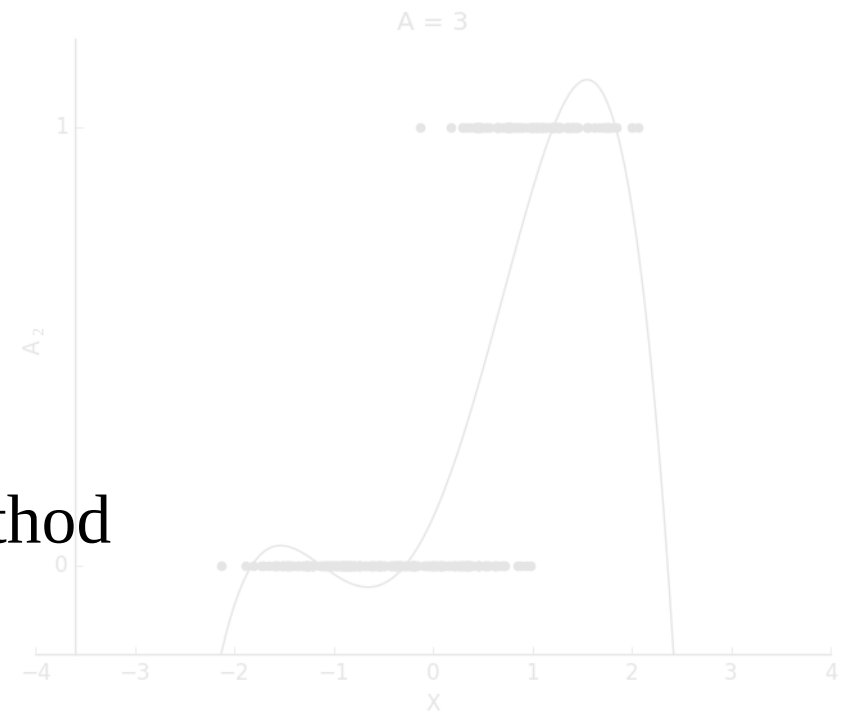
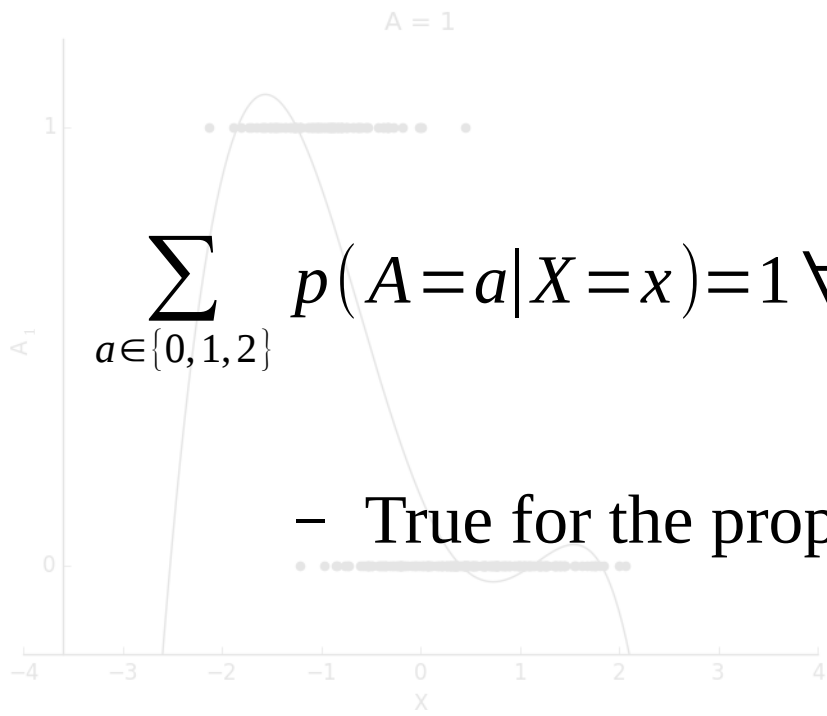
A = 2





$p(A=a|X=x) \geq 0 \forall a, x$

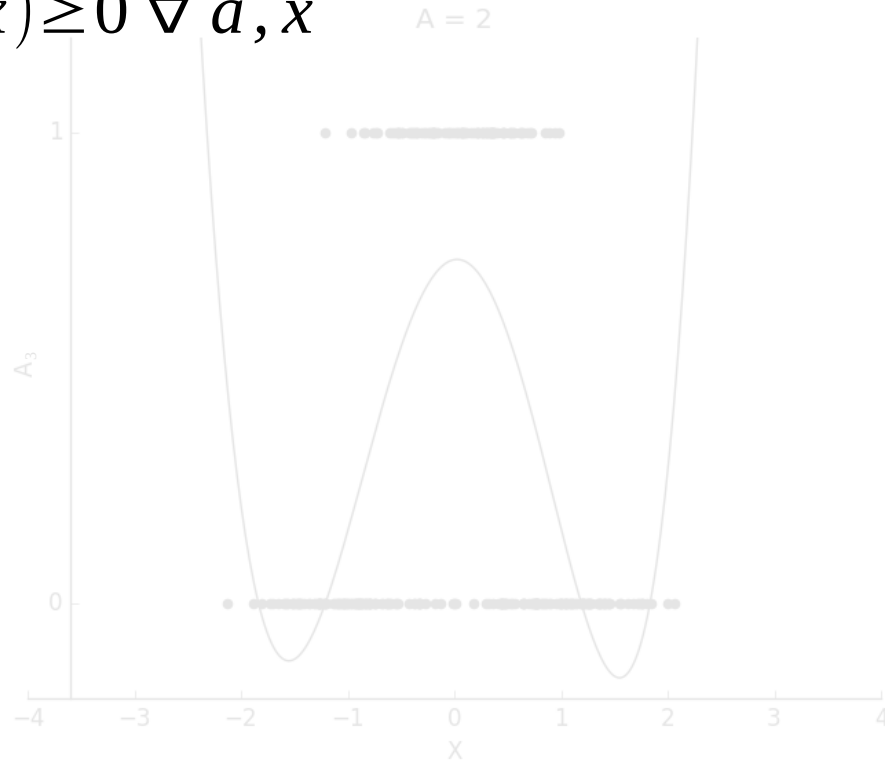


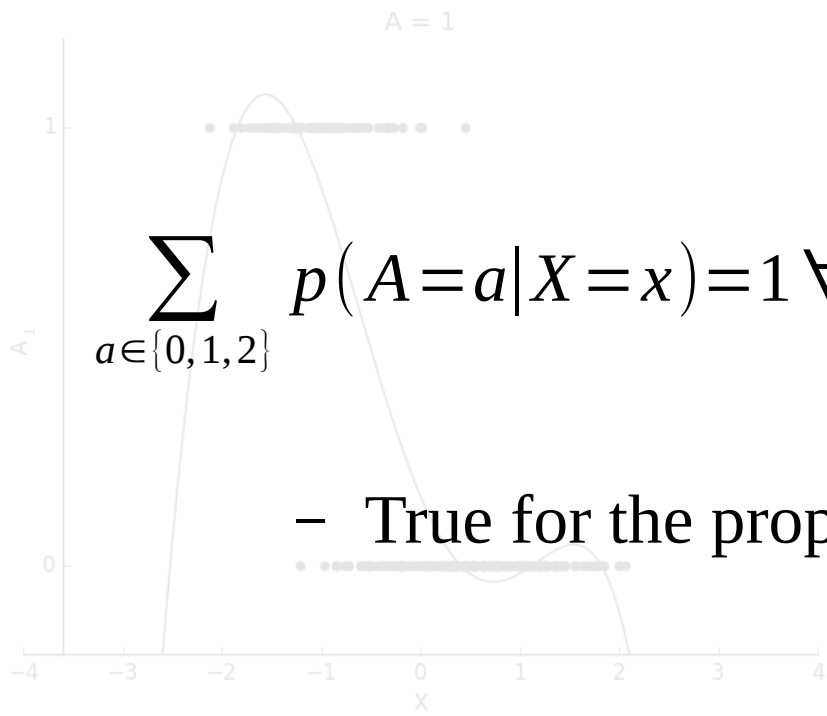


$$\sum_{a \in \{0,1,2\}} p(A=a|X=x) = 1 \forall x$$

- True for the proposed method

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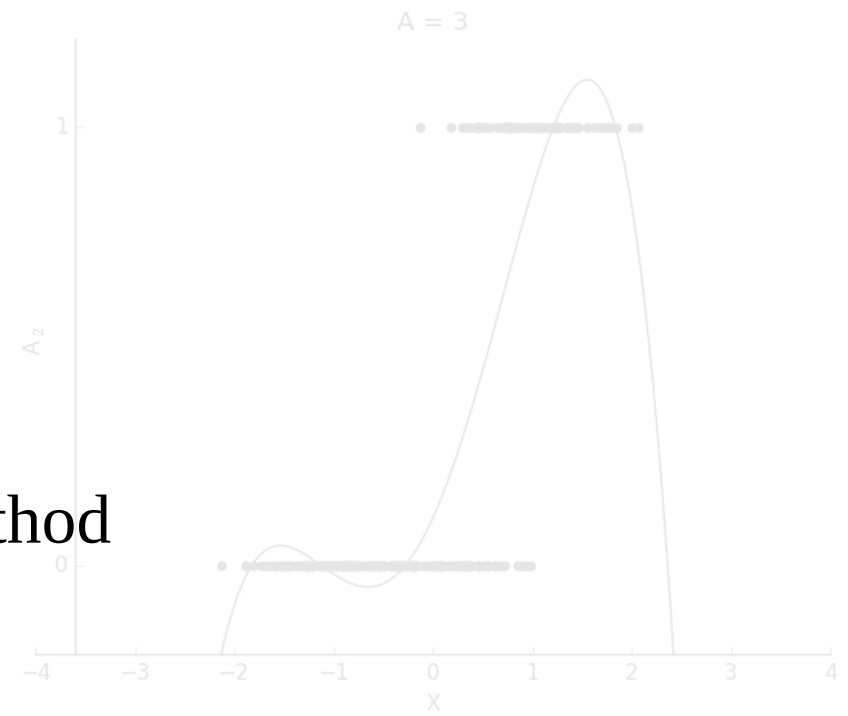




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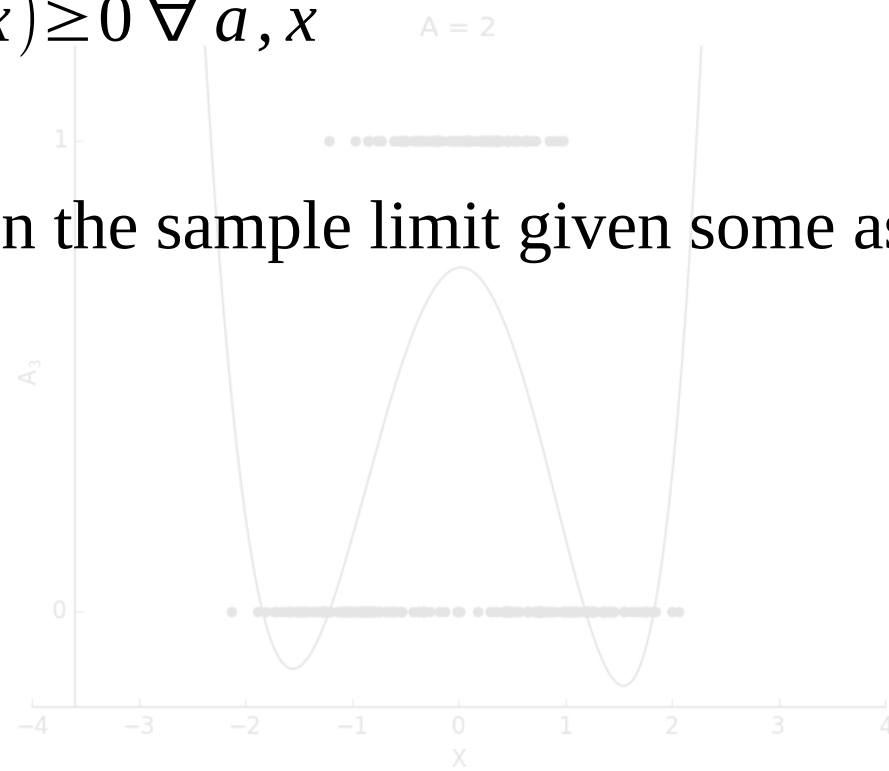
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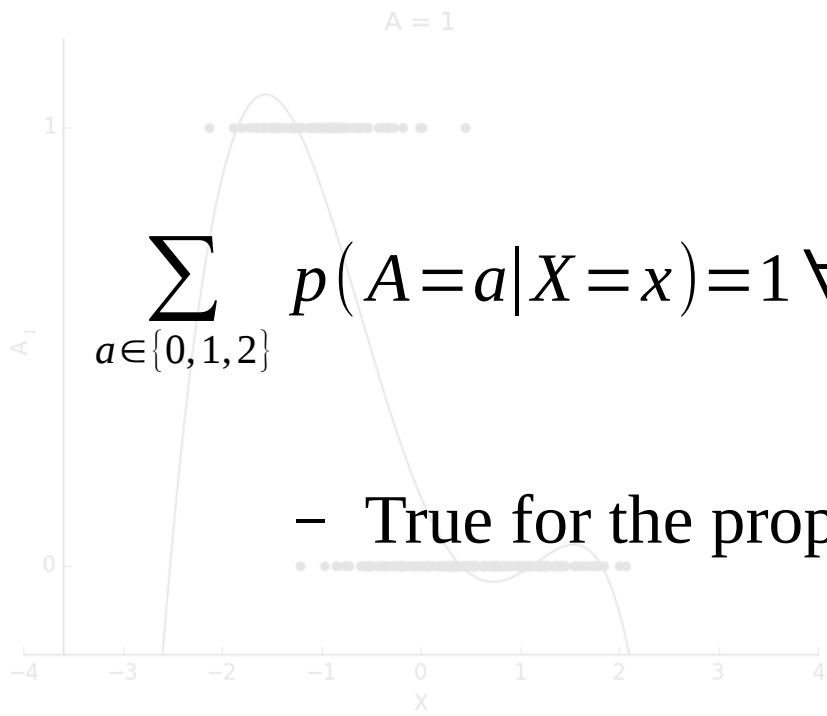
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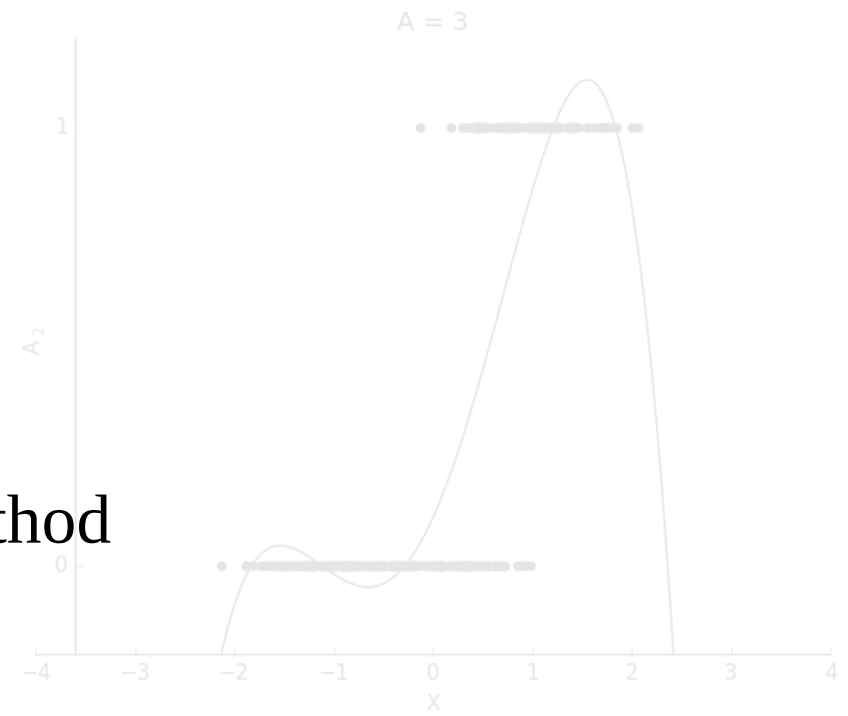




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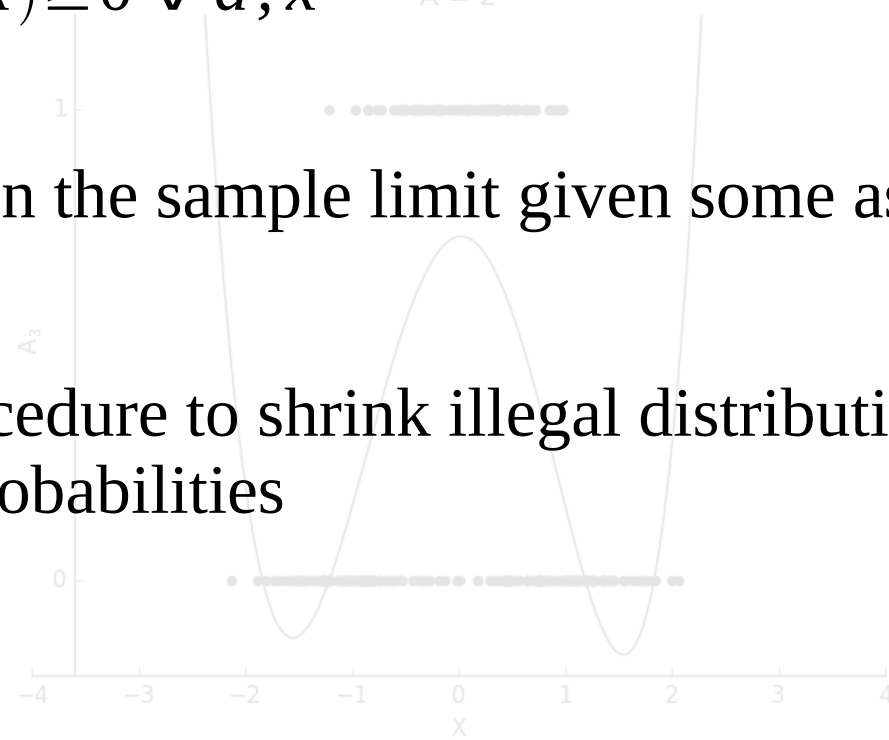
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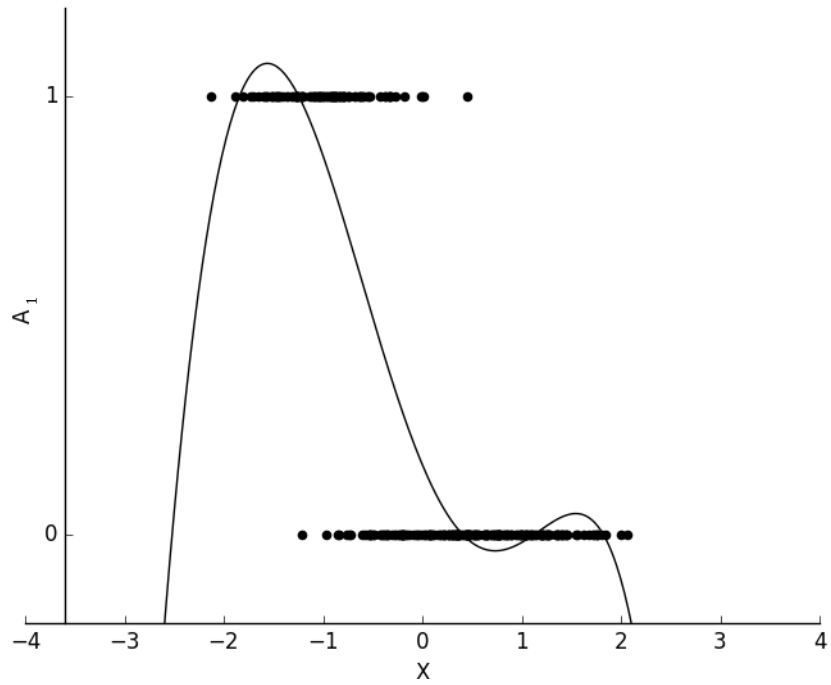
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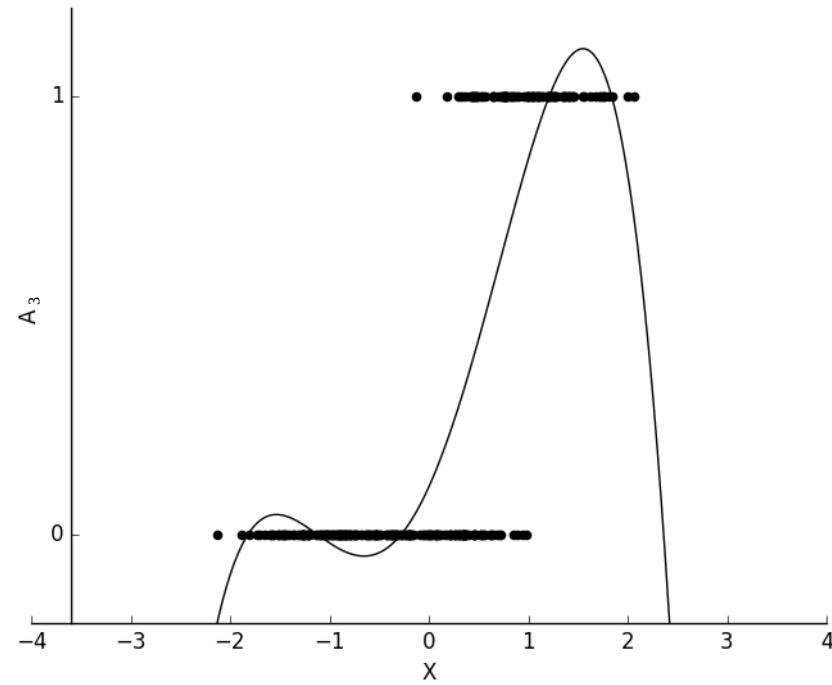
Define a procedure to shrink illegal distributions back into the domain of probabilities



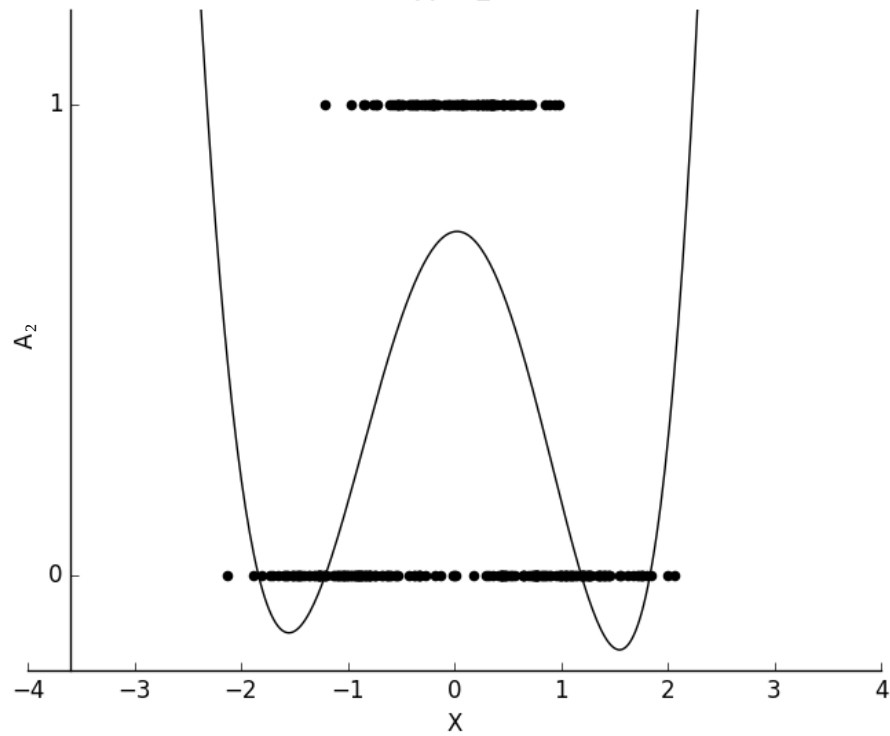
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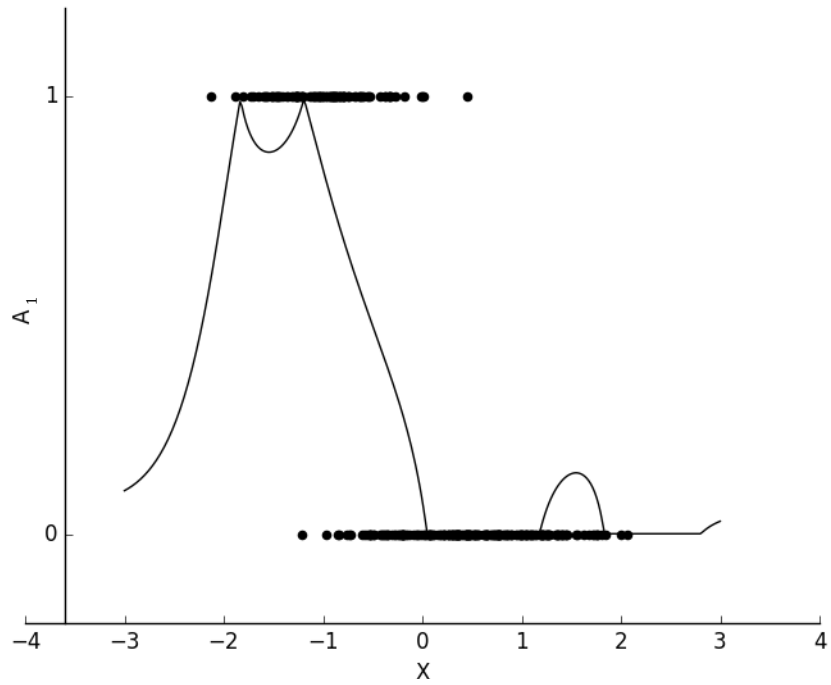
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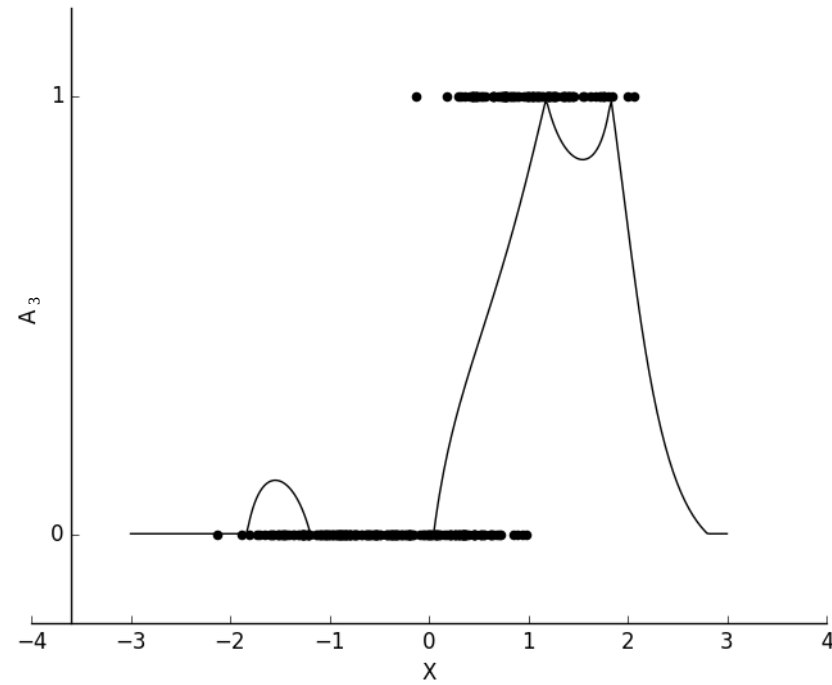
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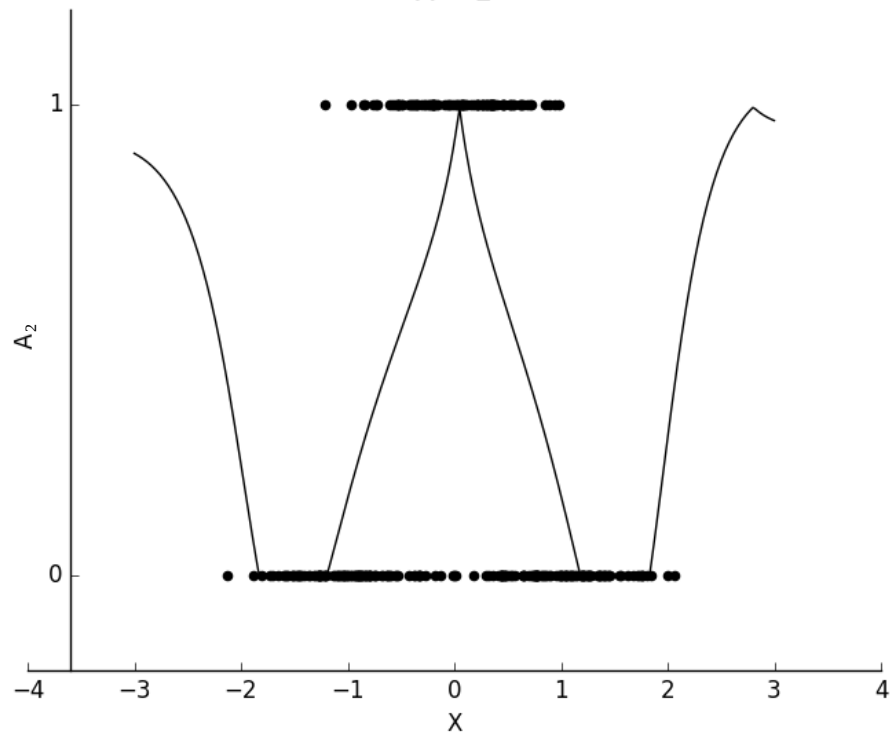
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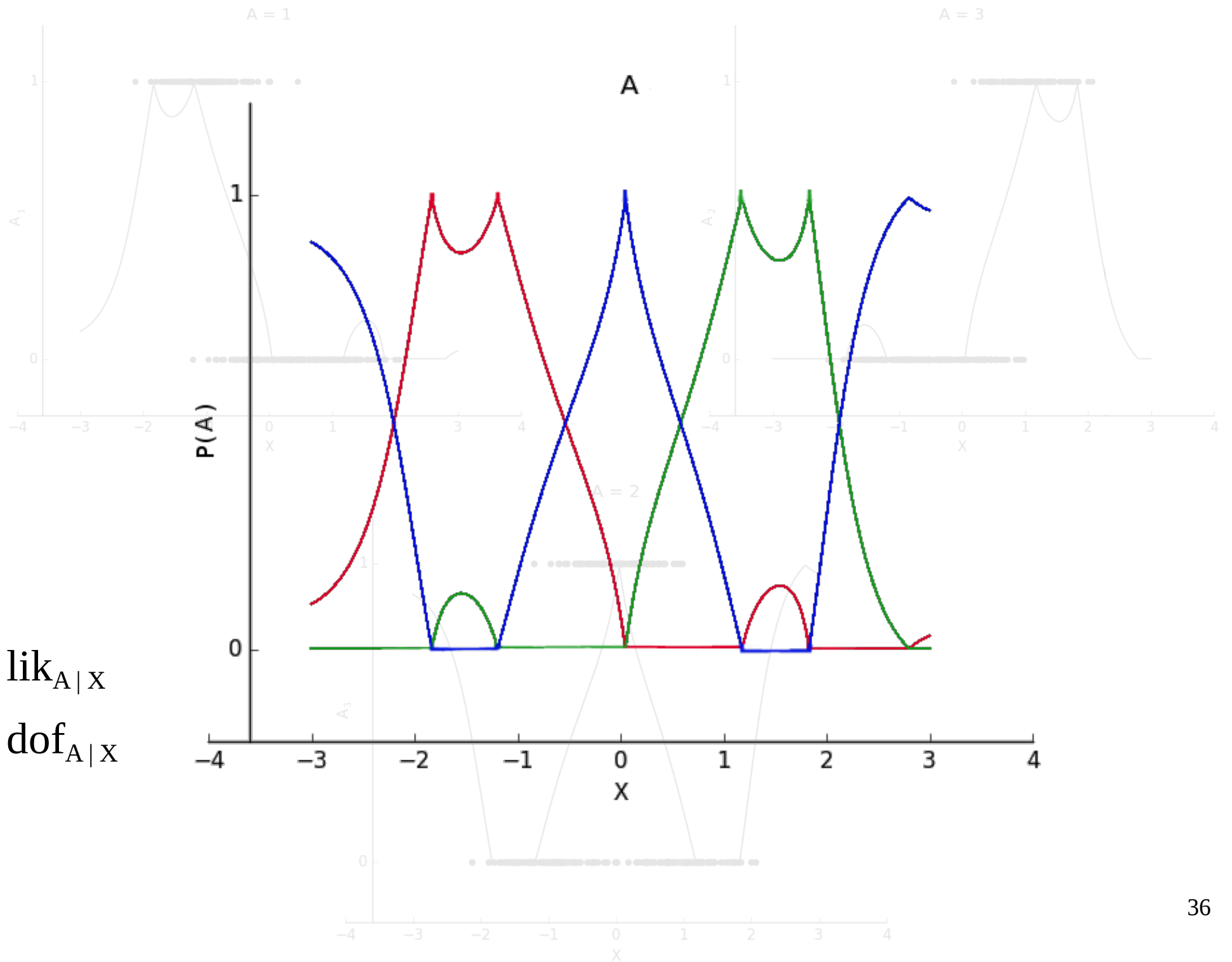


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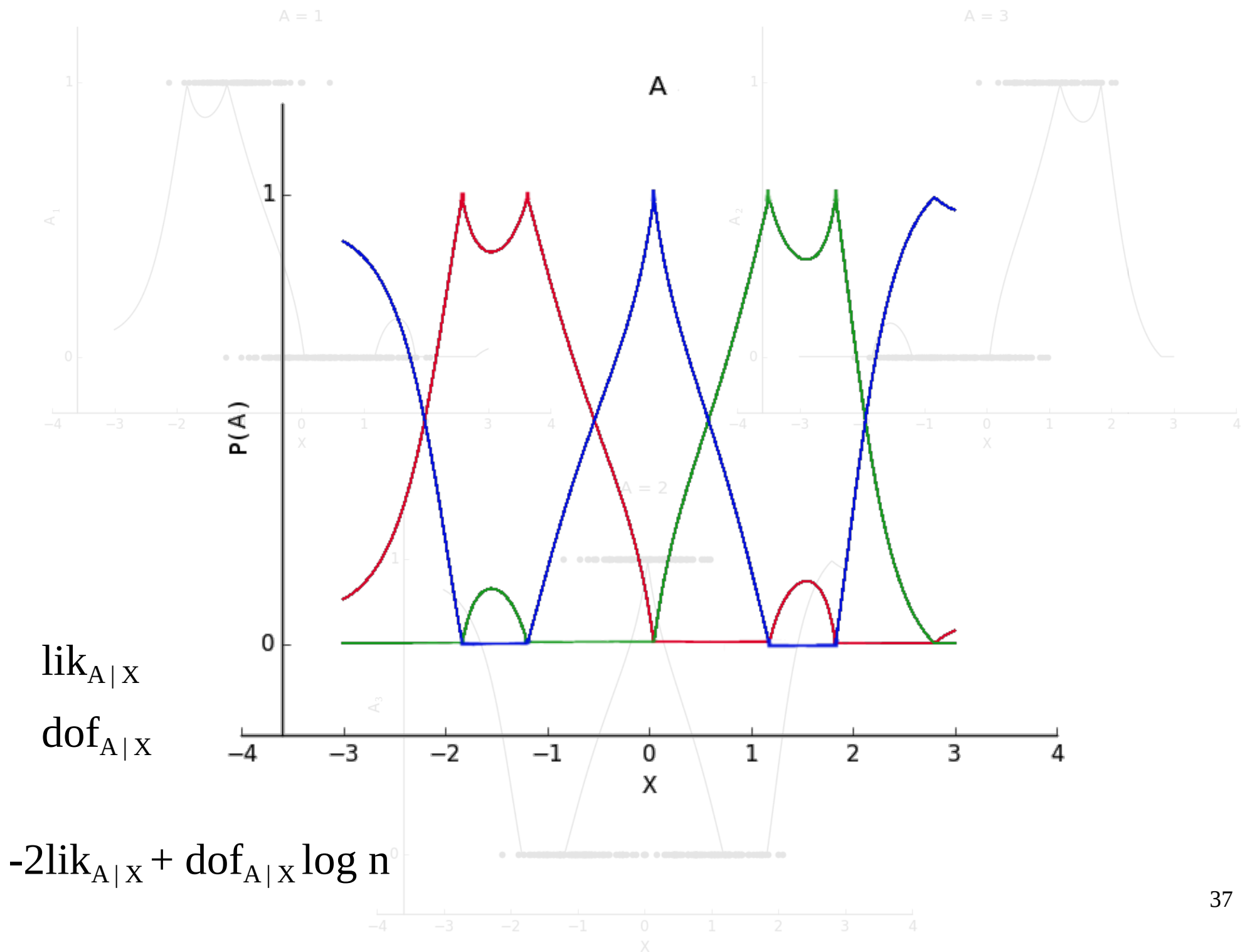
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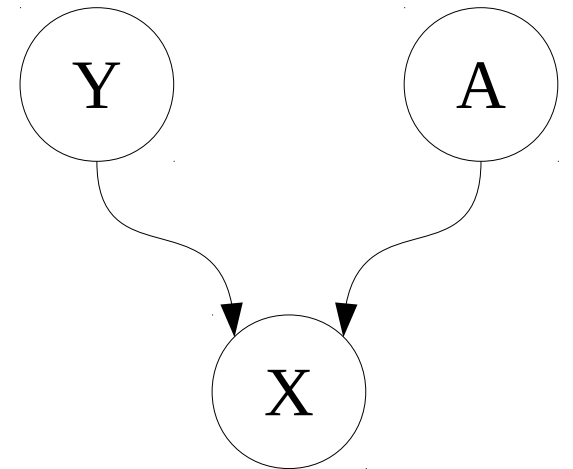
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Let  $X, Y$  be continuous  
Let  $A$  be discrete

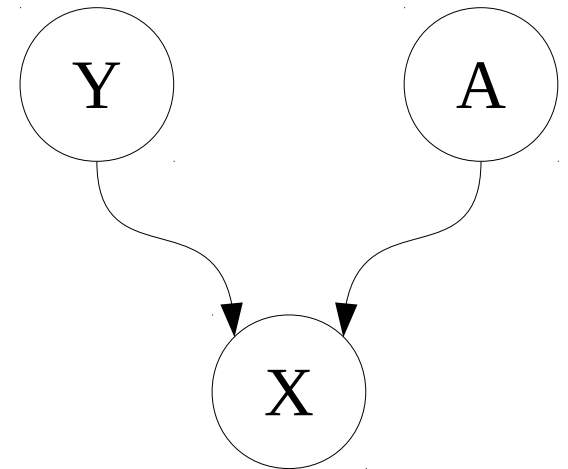


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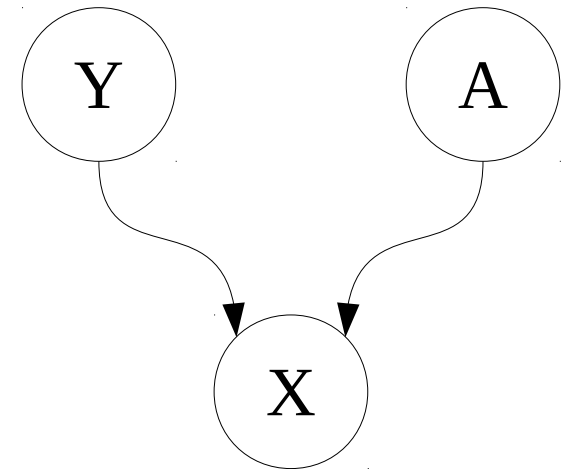


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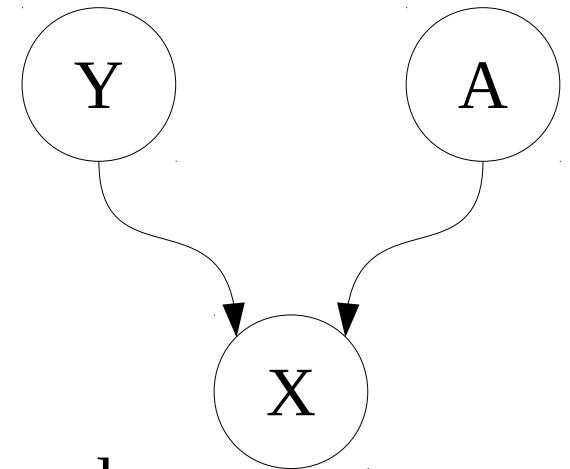
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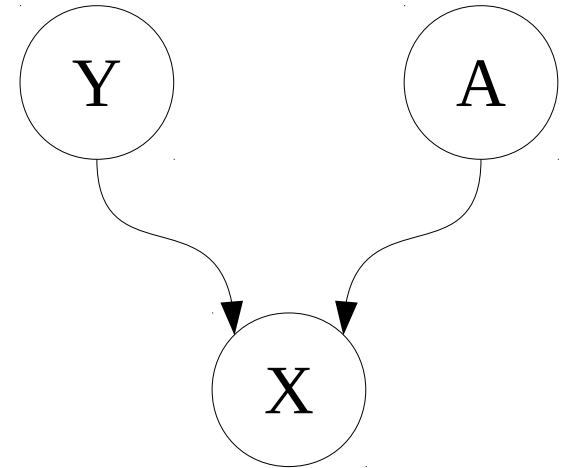
Partitioned  
Gaussians



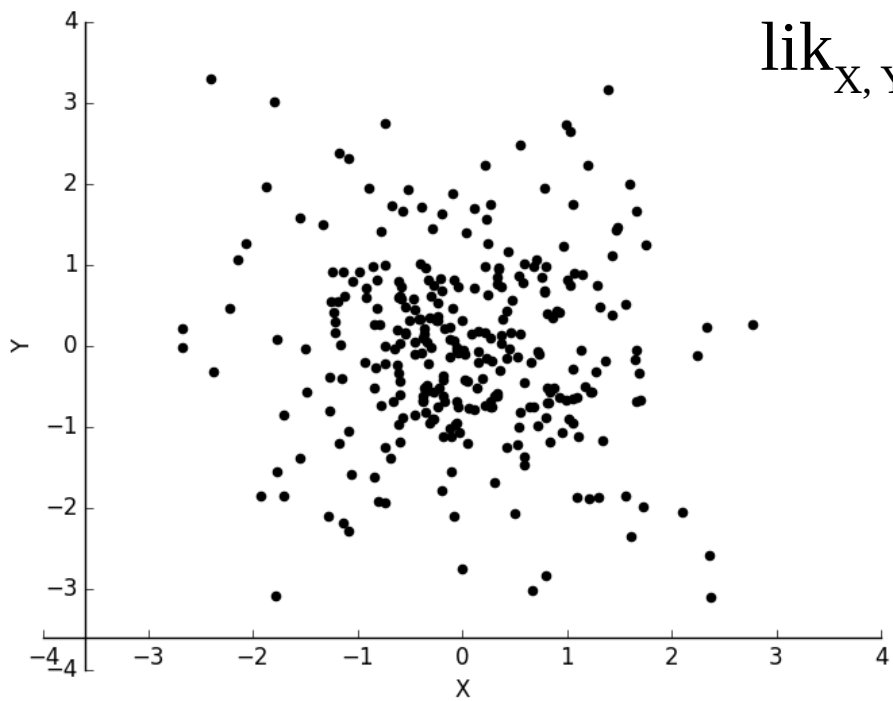
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- Want:  $\text{lik}_{X, Y|A}$ ,  $\text{dof}_{X, Y|A}$   
 $\text{lik}_{Y|A}$ ,  $\text{dof}_{Y|A}$

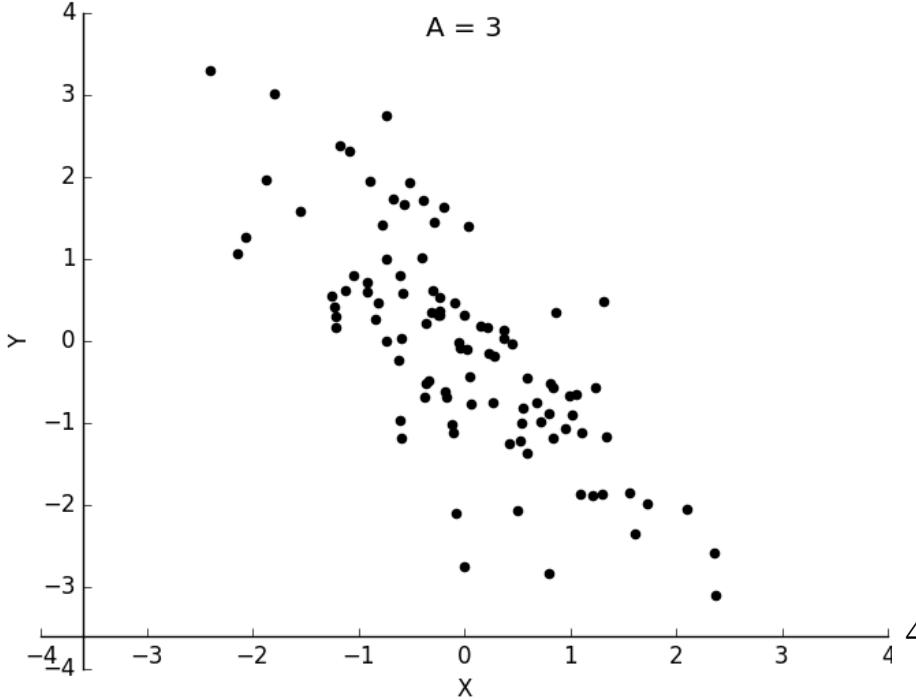
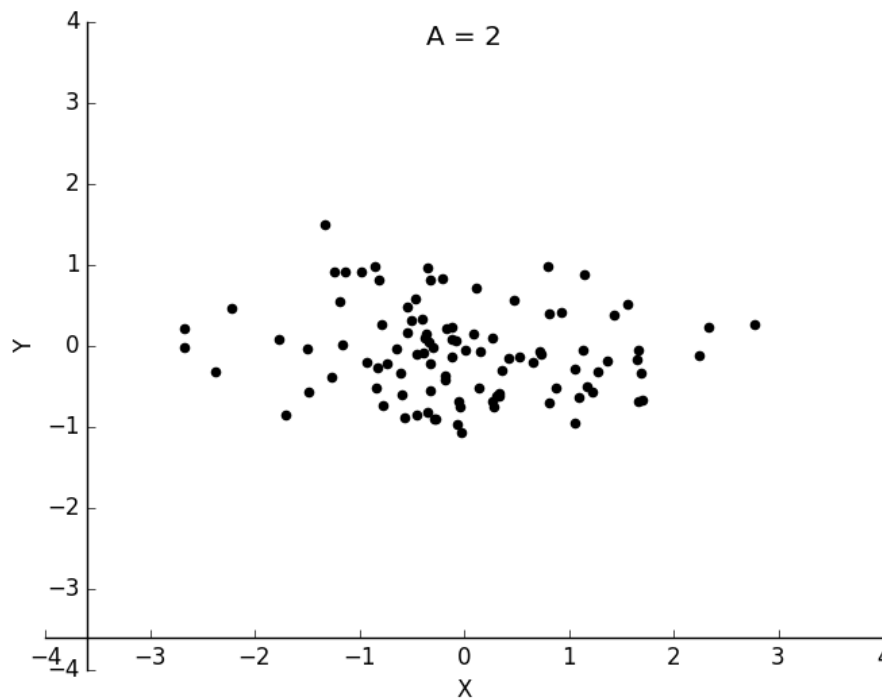
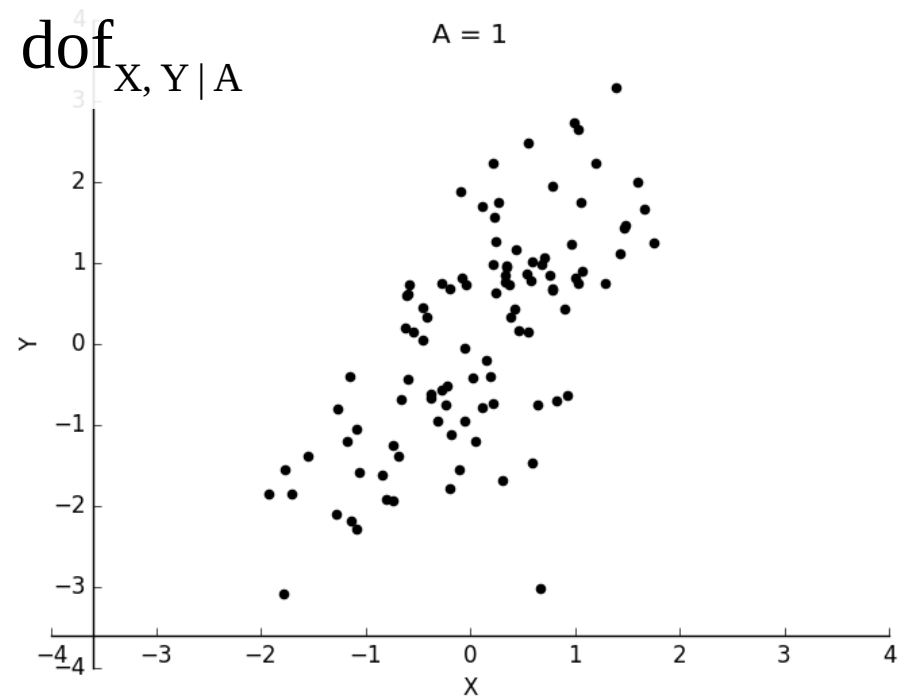
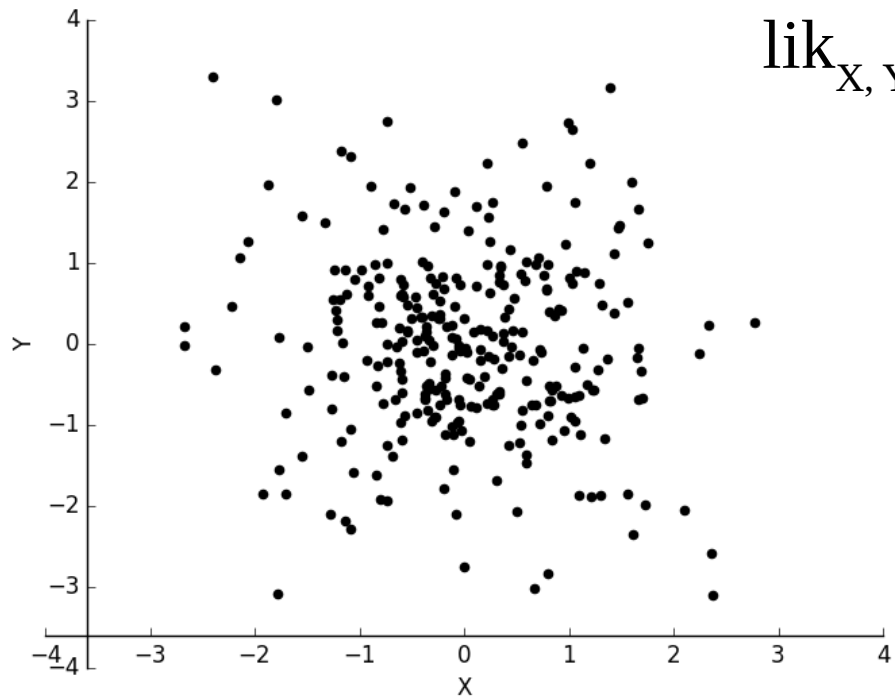
$$\frac{p(X, Y|A)}{p(Y|A)}$$

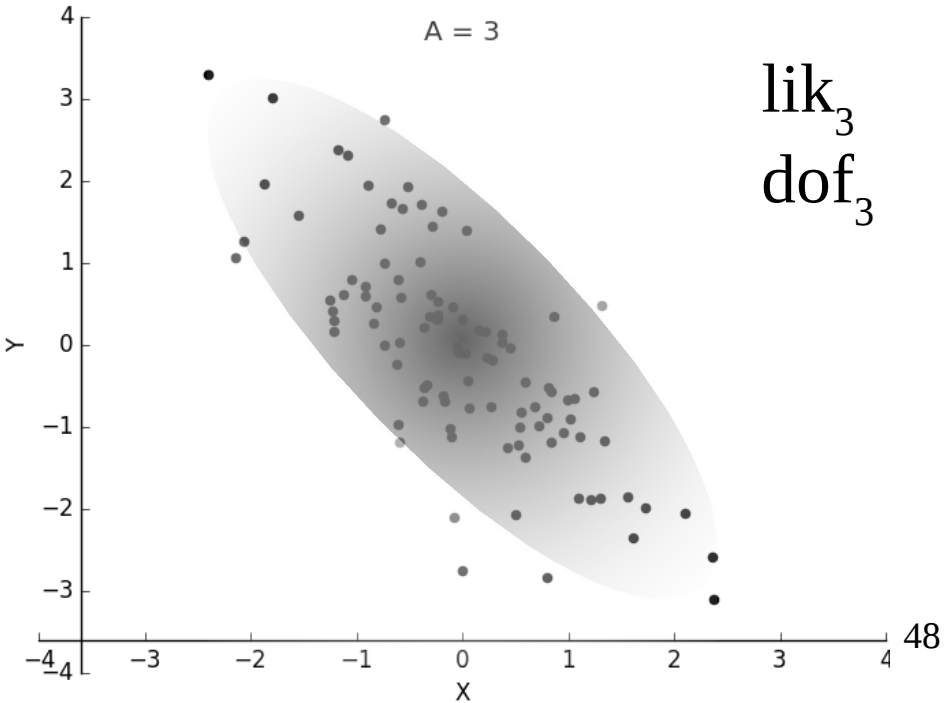
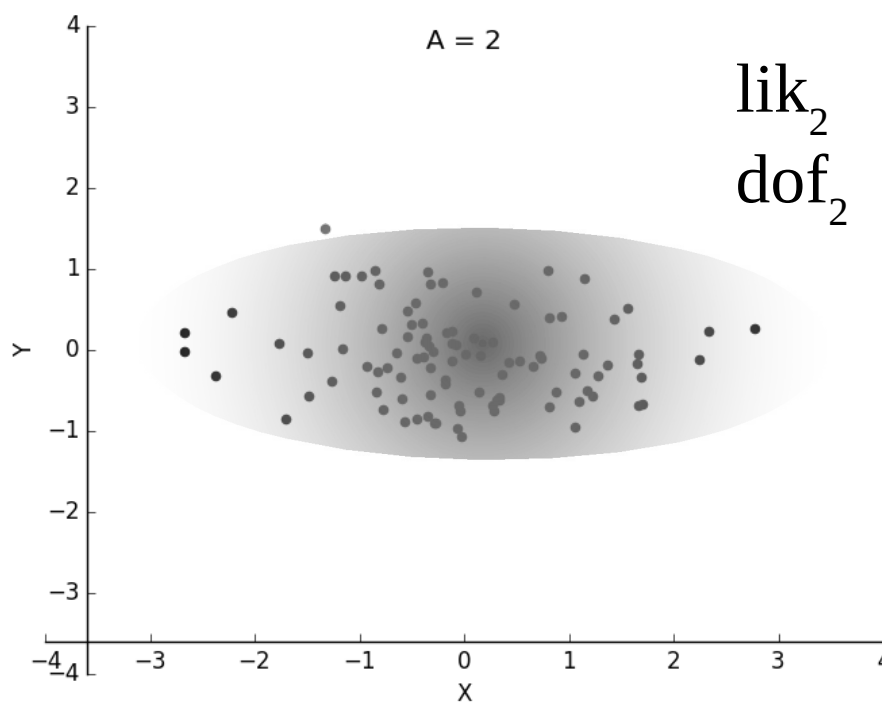
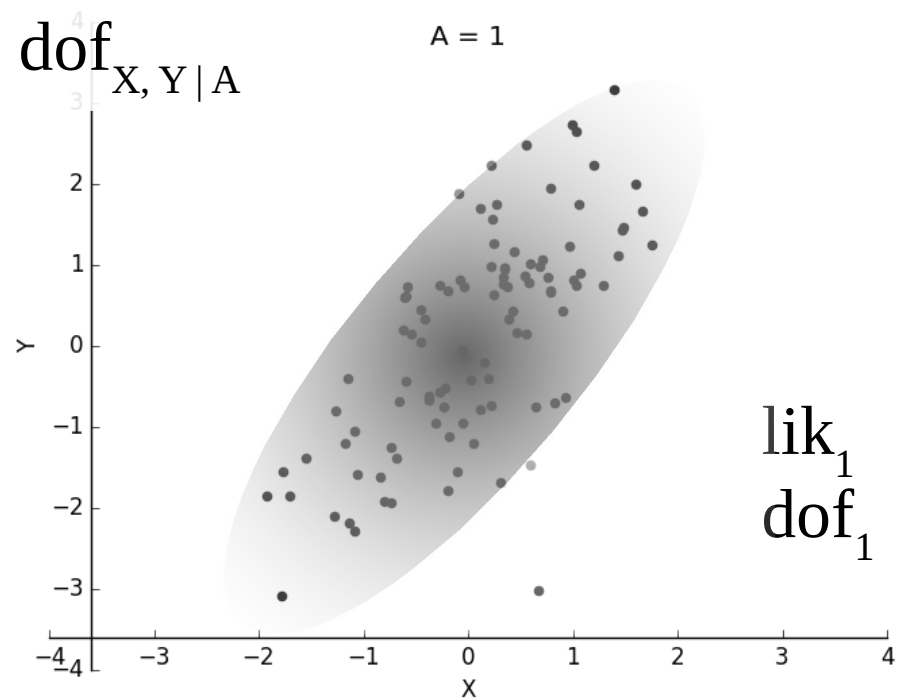
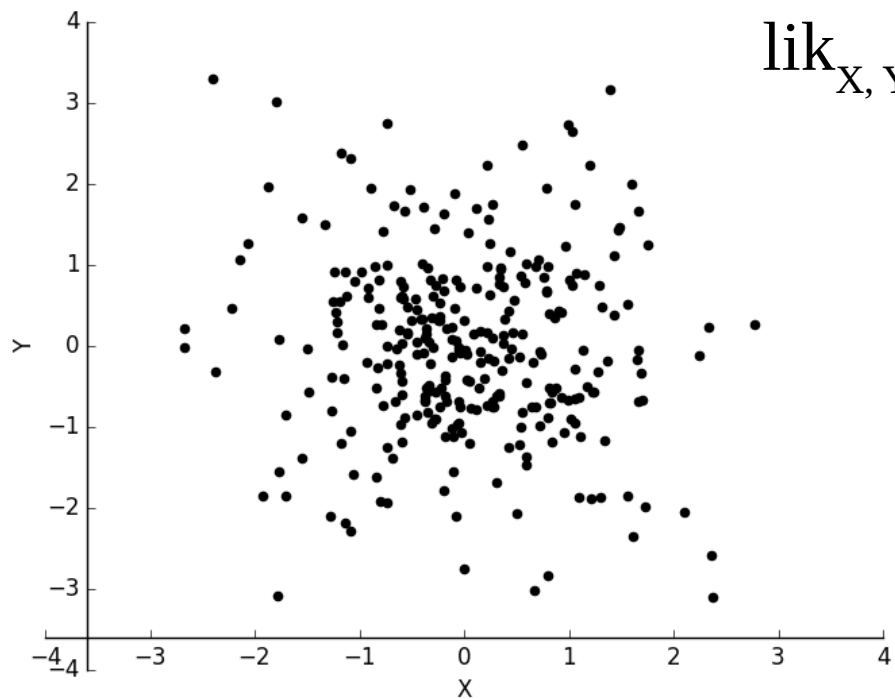


$\text{lik}_{X, Y|A}, \text{dof}_{X, Y|A}$

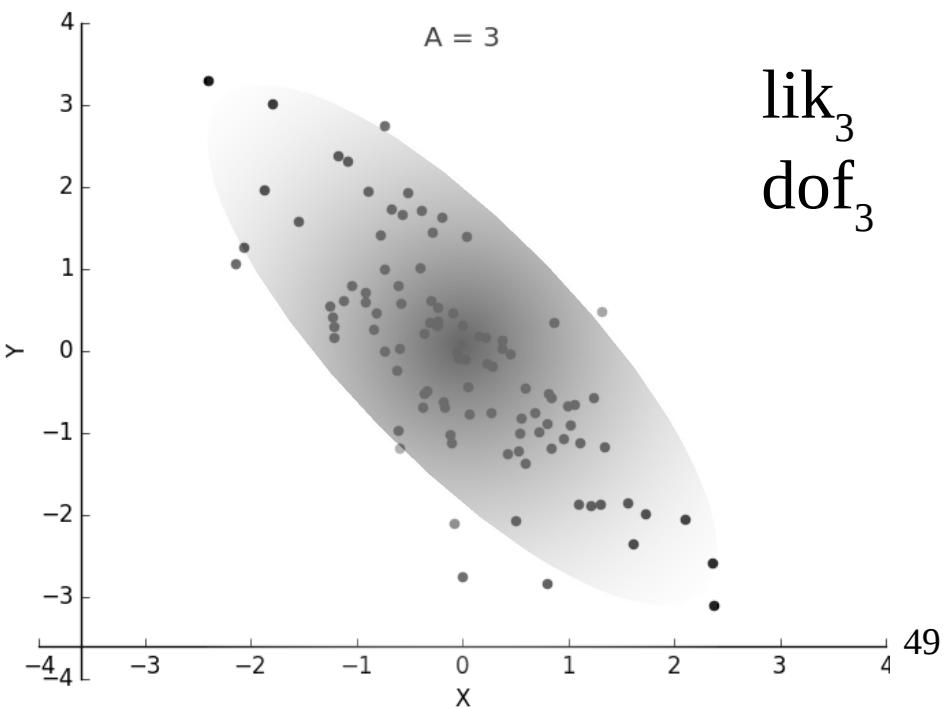
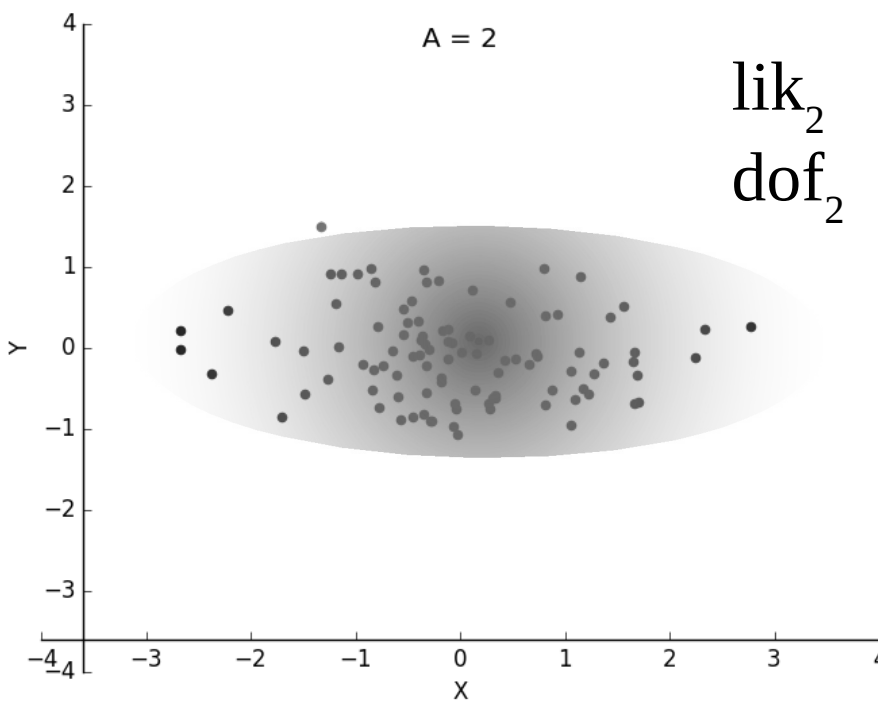
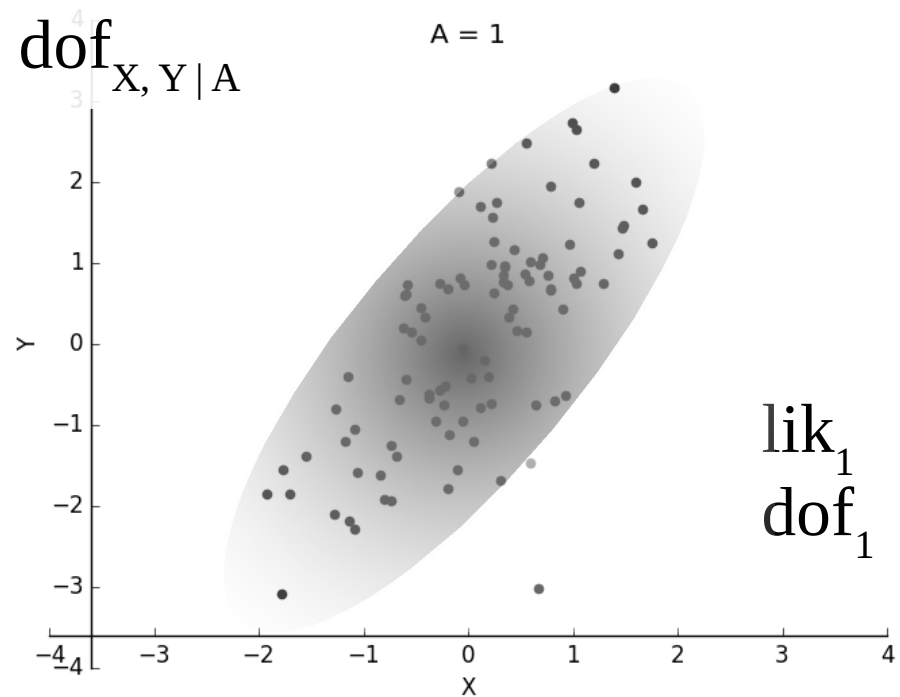
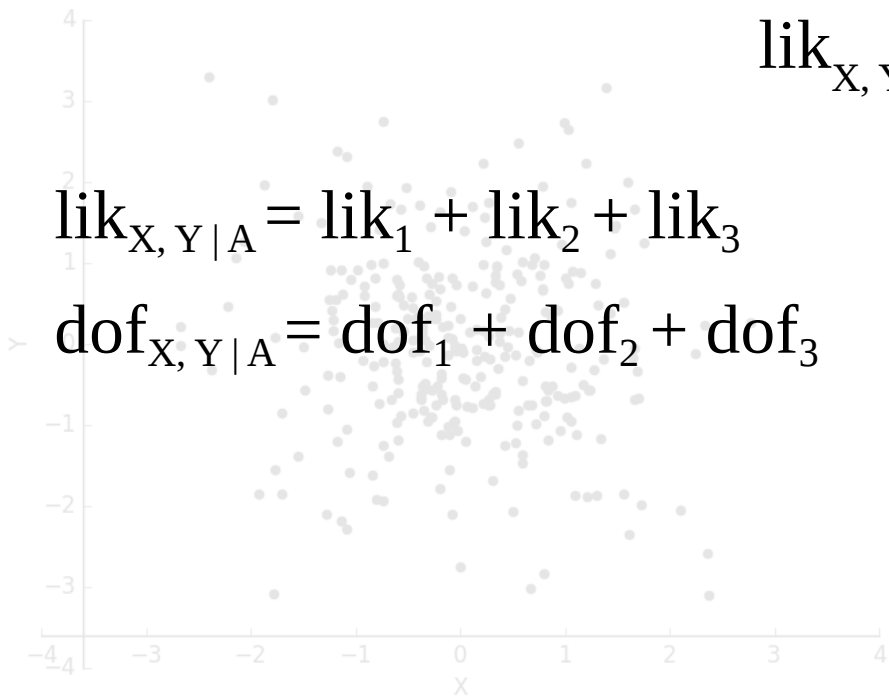


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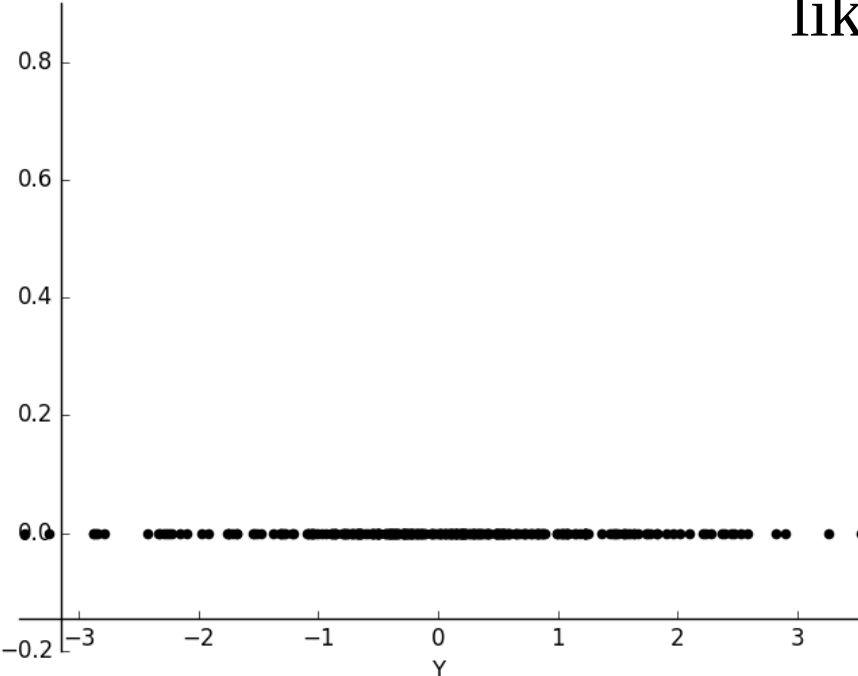






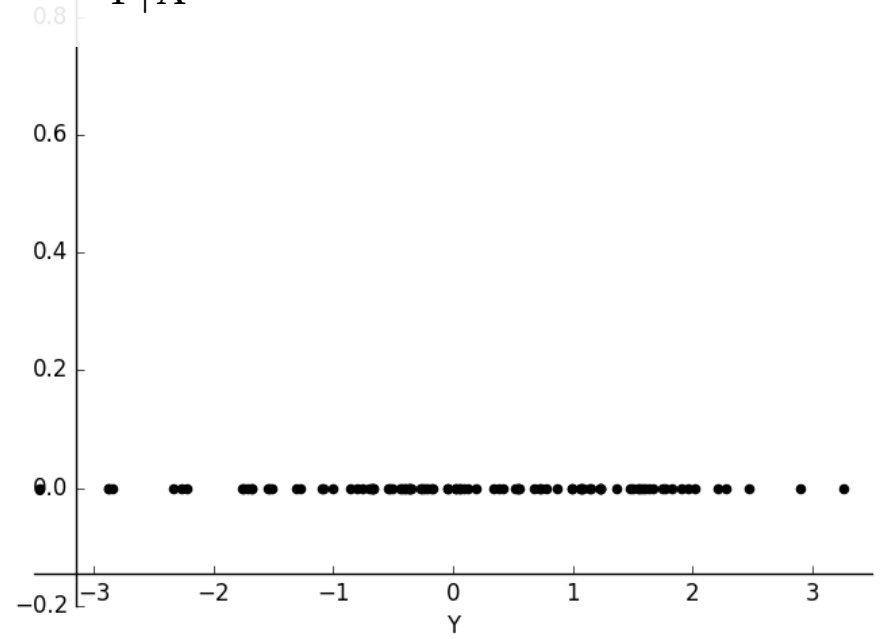
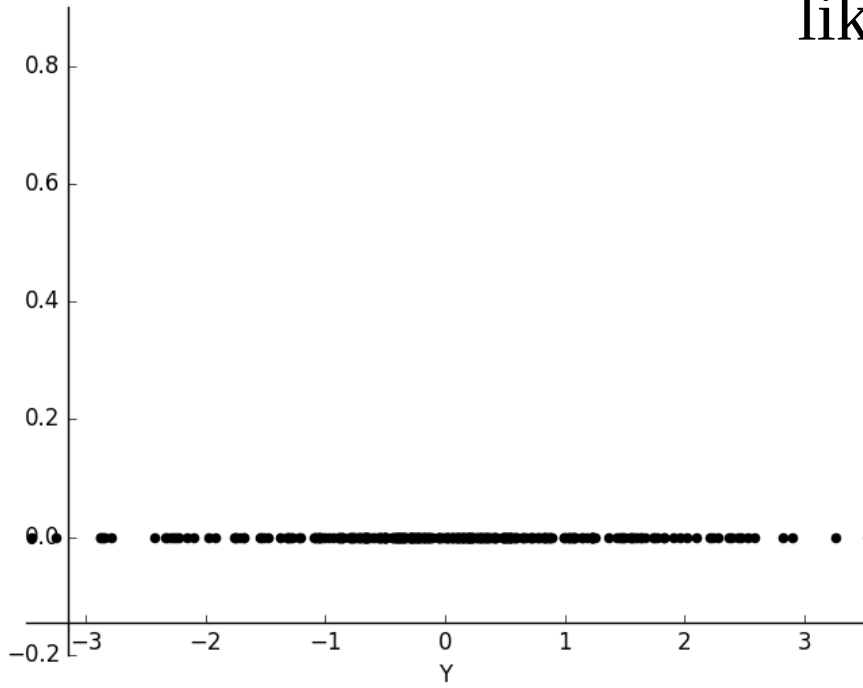


$\text{lik}_{Y|A}, \text{dof}_{Y|A}$

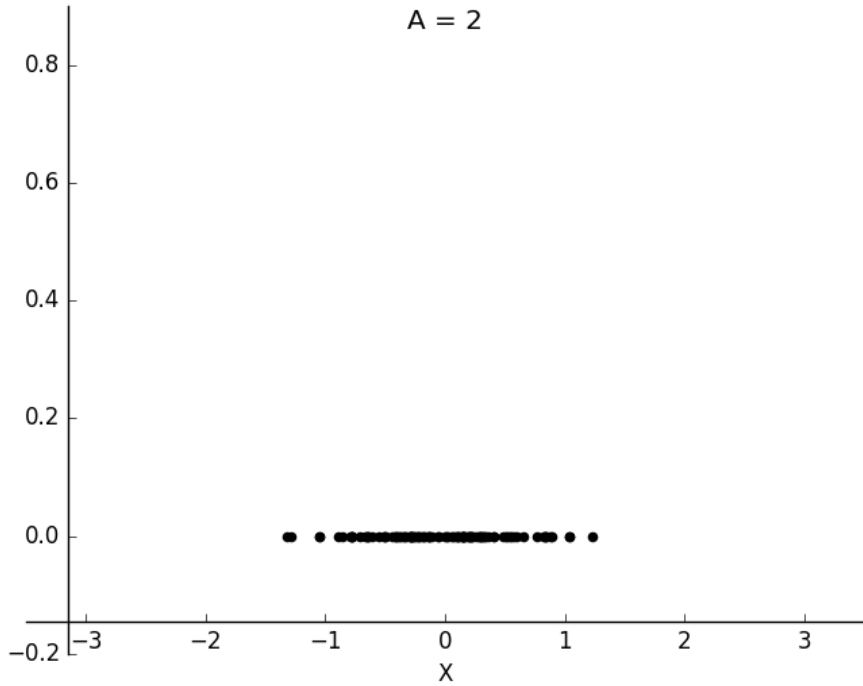


lik<sub>Y|A</sub>, dof<sub>Y|A</sub>

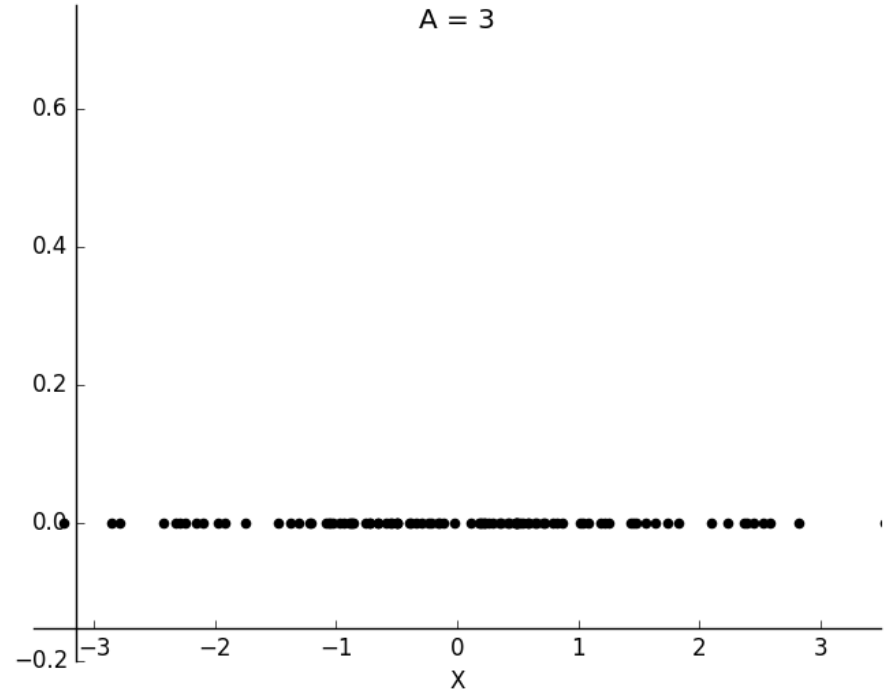
A = 1



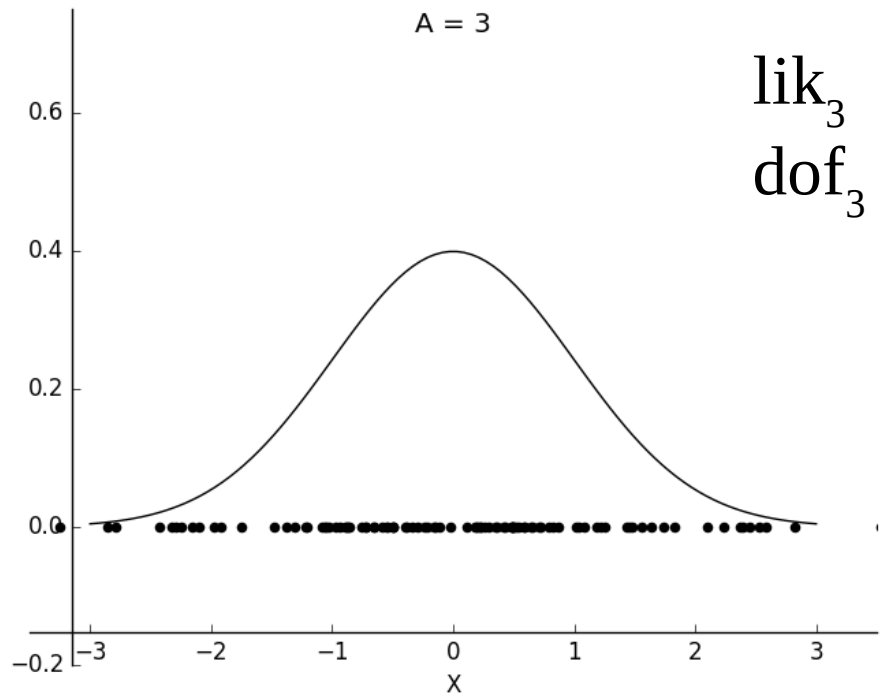
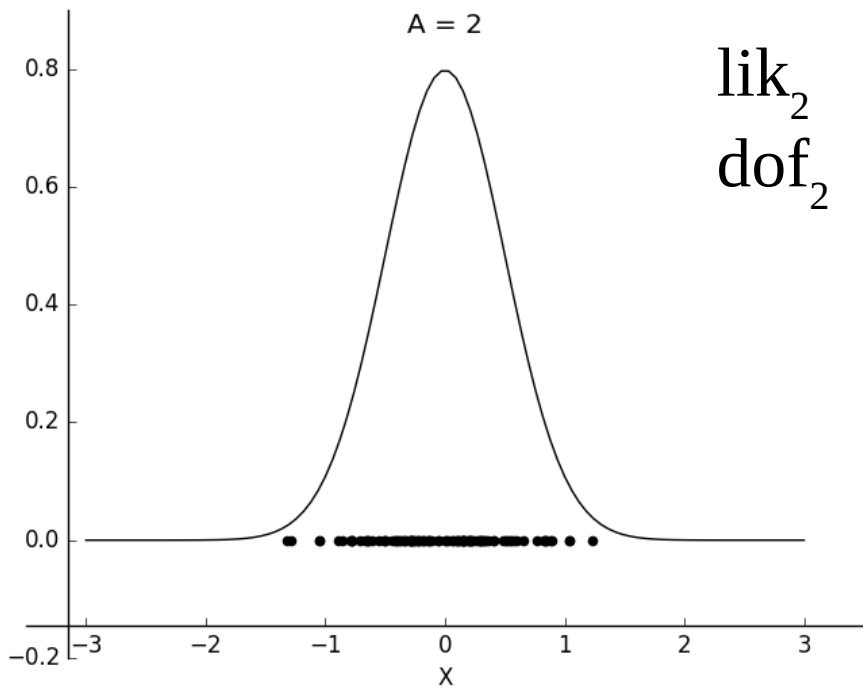
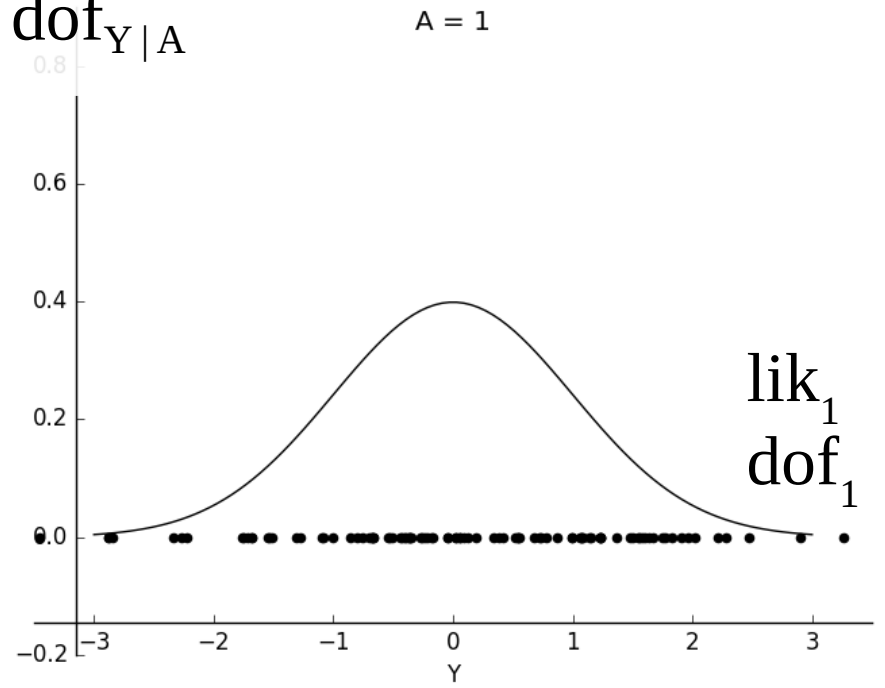
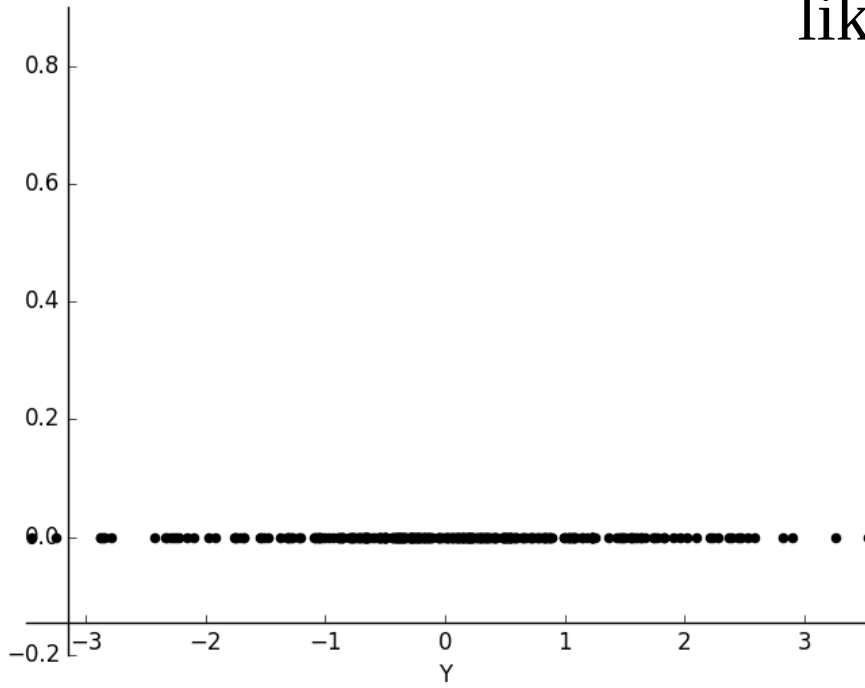
A = 2



A = 3

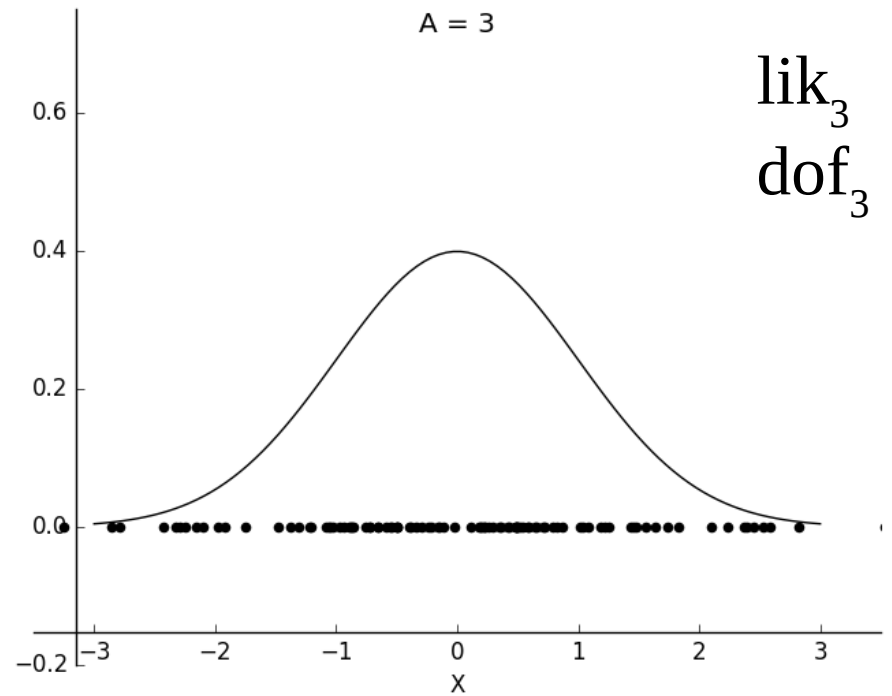
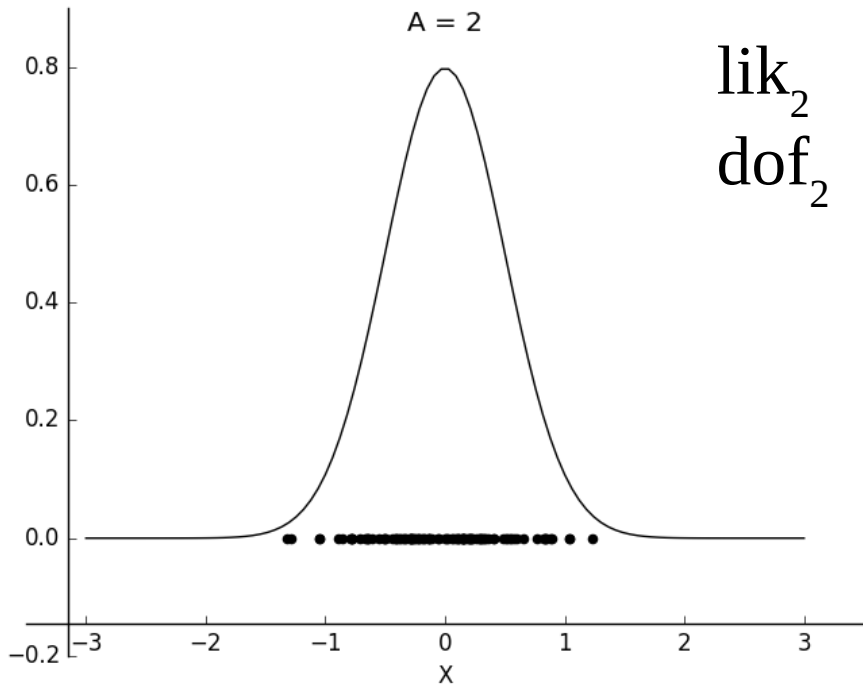
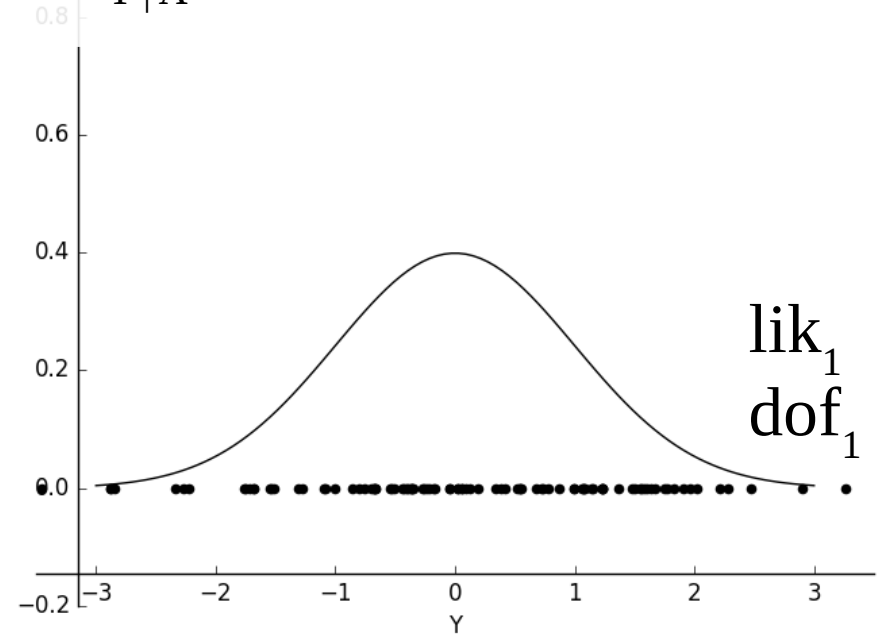
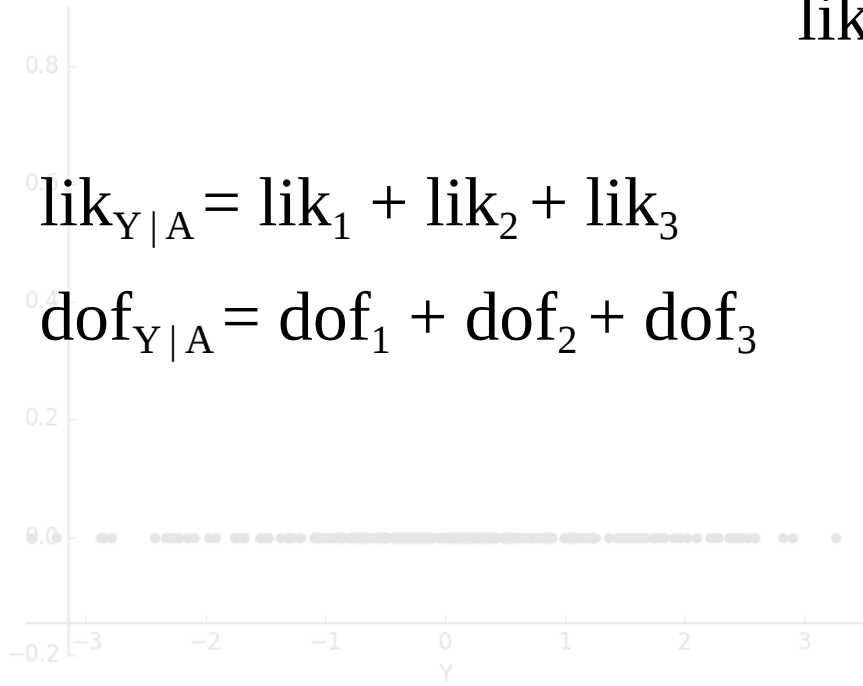


$\text{lik}_{Y|A}, \text{dof}_{Y|A}$



$\text{lik}_{Y|A}, \text{dof}_{Y|A}$

$A = 1$



# Modeling a Continuous Child

Have:  $\text{lik}_{X, Y|A}$ ,  $\text{dof}_{X, Y|A}$   
 $\text{lik}_{Y|A}$ ,  $\text{dof}_{Y|A}$

$$\frac{p(X, Y|A)}{p(Y|A)}$$

# Modeling a Continuous Child

Have:  $\text{lik}_{X, Y|A}$ ,  $\text{dof}_{X, Y|A}$   
 $\text{lik}_{Y|A}$ ,  $\text{dof}_{Y|A}$

$$\frac{p(X, Y|A)}{p(Y|A)}$$

$$\text{lik}_{X|Y, A} = \text{lik}_{X, Y|A} - \text{lik}_{Y|A}$$
$$\text{dof}_{X|Y, A} = \text{dof}_{X, Y|A} - \text{dof}_{Y|A}$$

# Modeling a Continuous Child

Have:  $\text{lik}_{X, Y|A}$ ,  $\text{dof}_{X, Y|A}$   
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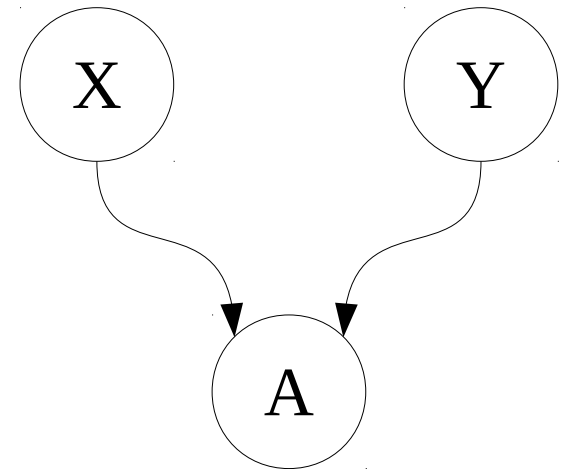
$$-2\text{lik}_{X|Y, A} + \text{dof}_{X|Y, A} \log n$$



# Modeling a Discrete Child

Assume  $X, Y$  are  
parents of  $A$

Let  $X, Y$  be continuous  
Let  $A$  be discrete

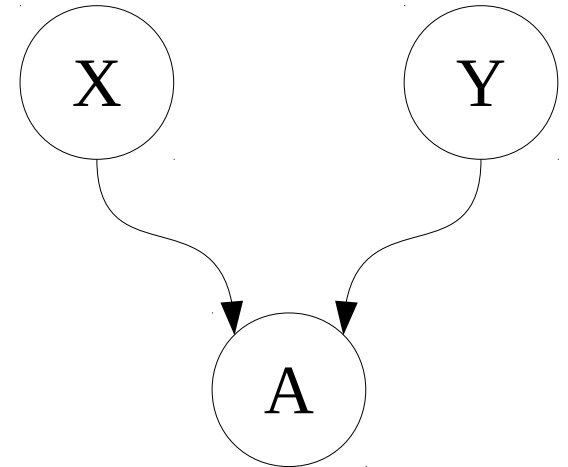


# Modeling a Discrete Child

Assume  $X, Y$  are  
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Let  $X, Y$  be continuous  
Let  $A$  be discrete

$$p(A|X, Y) = \frac{p(X, Y, A)}{p(X, Y)}$$

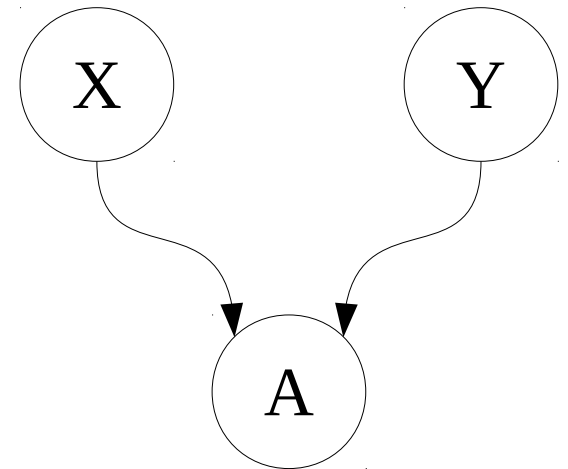


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Let  $X, Y$  be continuous  
Let  $A$  be discrete

$$\begin{aligned} p(A|X, Y) &= \frac{p(X, Y, A)}{p(X, Y)} \\ &= \frac{p(X, Y|A)p(A)}{p(X, Y)} \end{aligned}$$

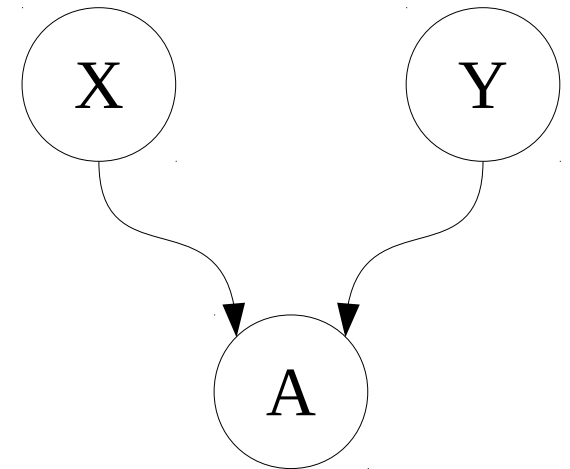


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$$= \frac{p(X, Y|A)p(A)}{p(X, Y)}$$



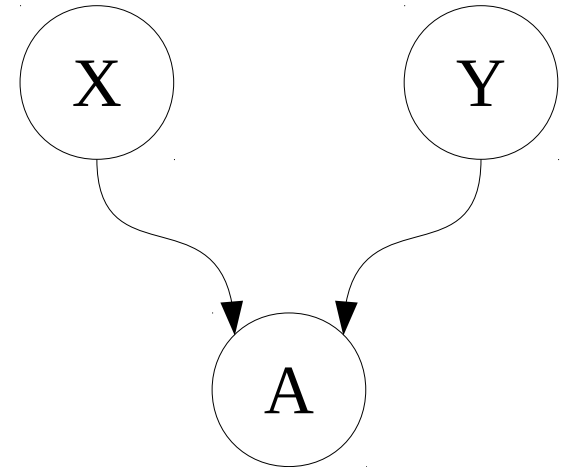
Partitioned  
Gaussians

Multinomial

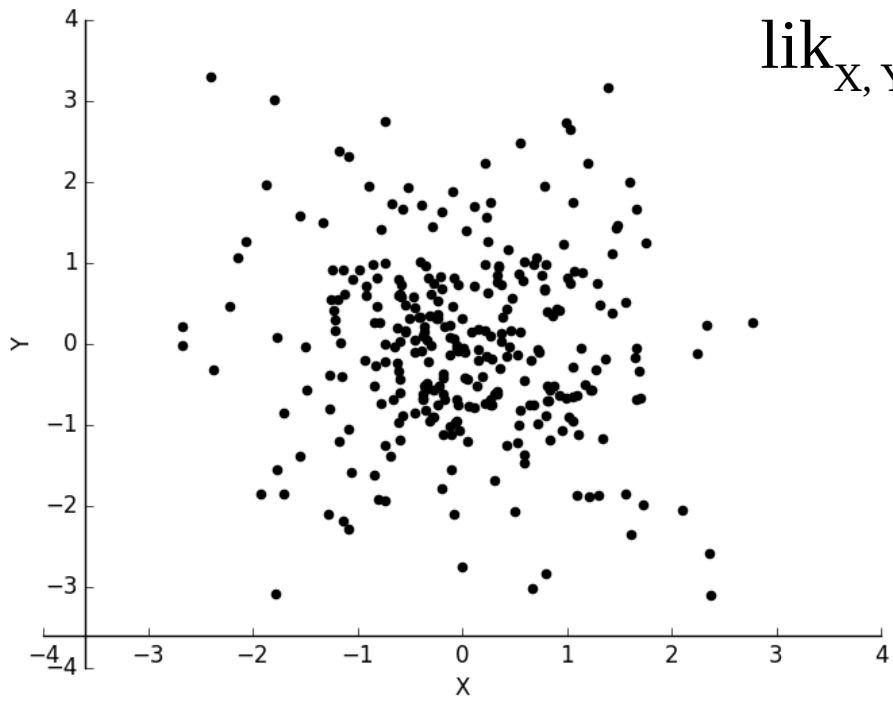
# Modeling a Discrete Child

- Want:  $\text{lik}_{X, Y|A}$ ,  $\text{dof}_{X, Y|A}$   
 $\text{lik}_A$ ,  $\text{dof}_A$   
 $\text{lik}_{X, Y}$ ,  $\text{dof}_{X, Y}$

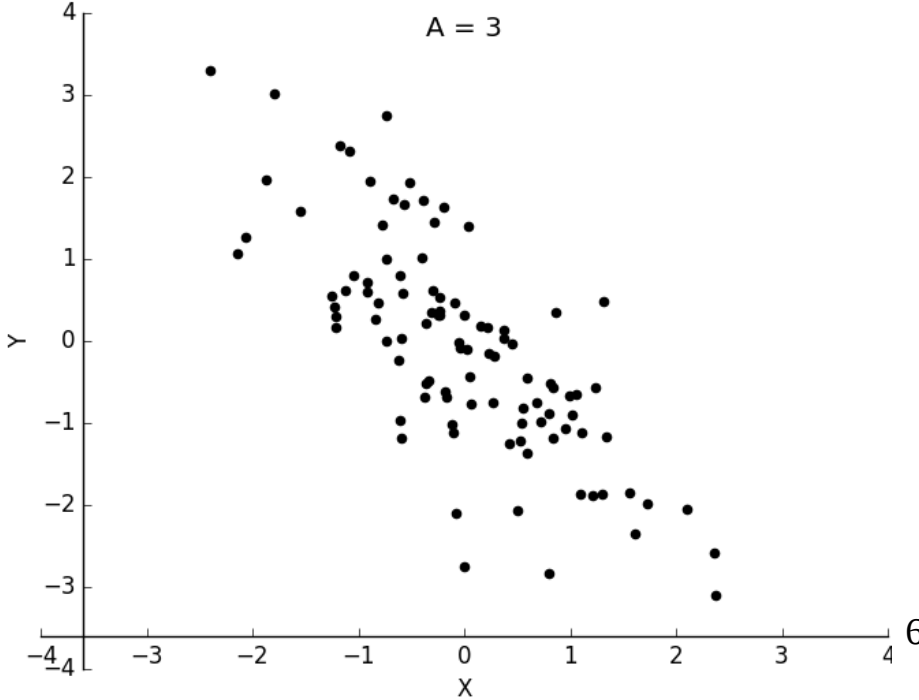
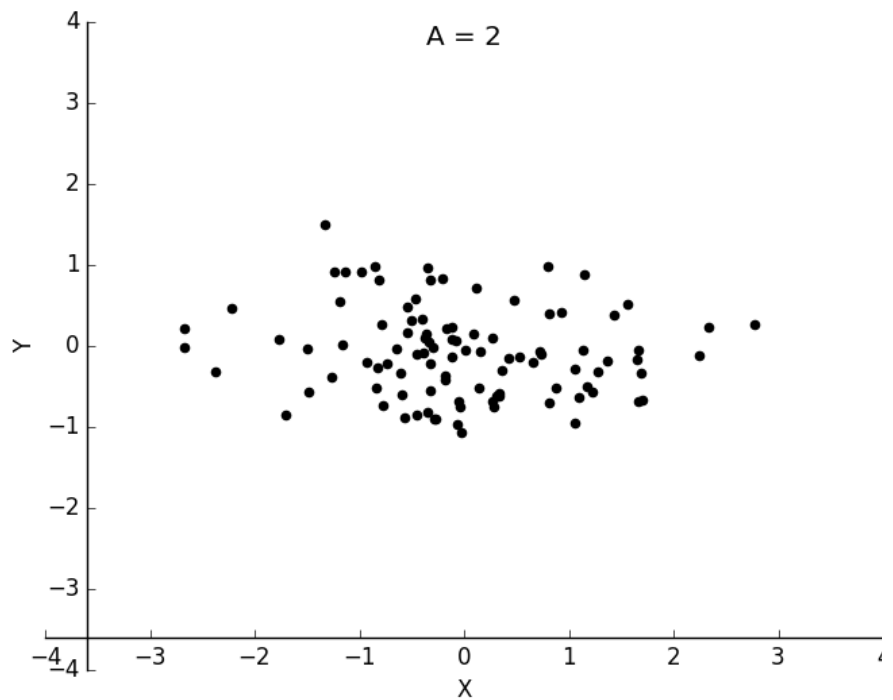
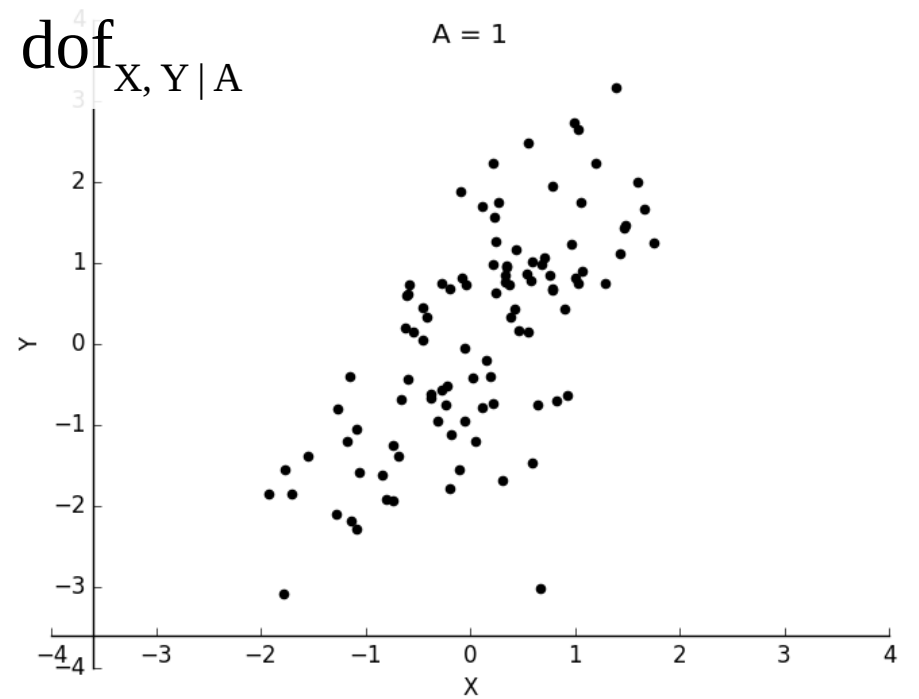
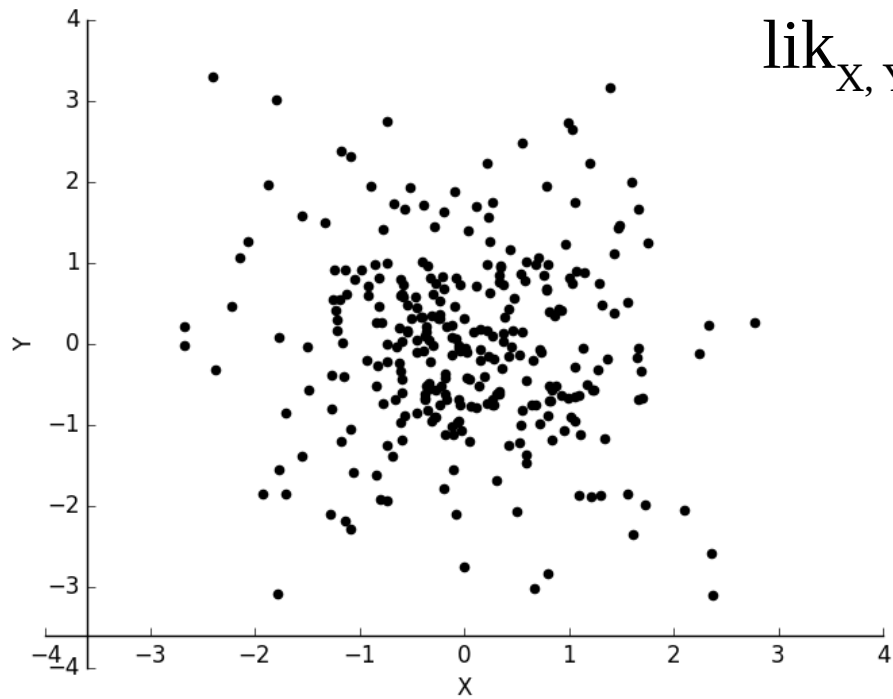
$$\frac{p(X, Y|A)p(A)}{p(X, Y)}$$

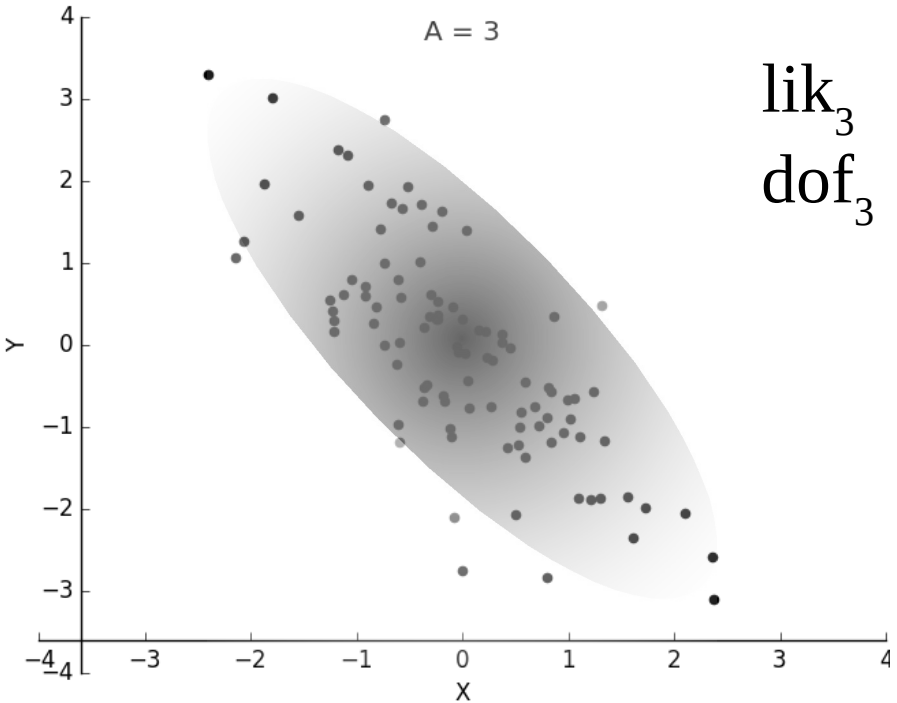
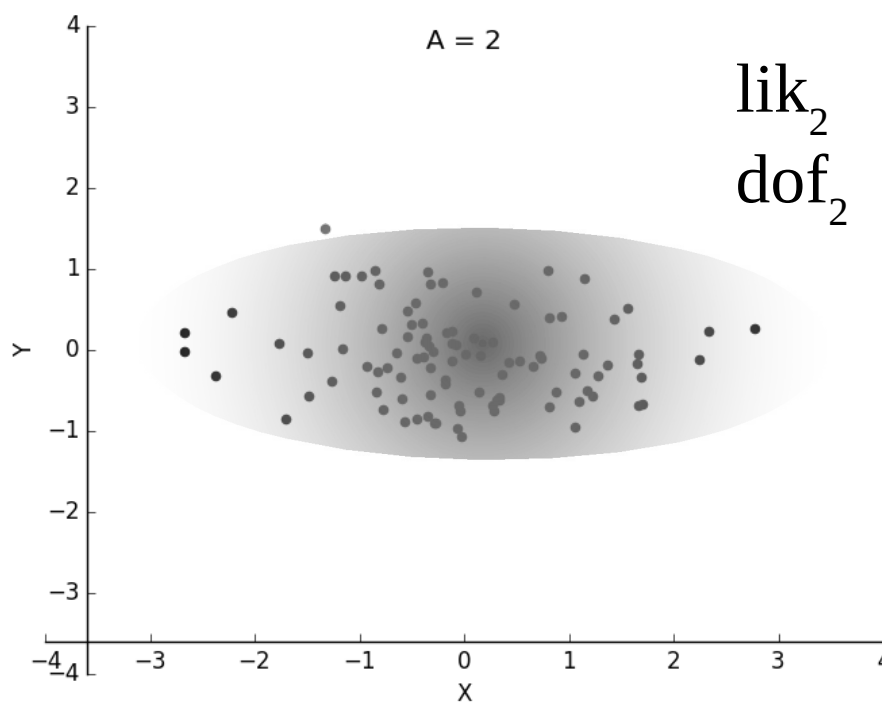
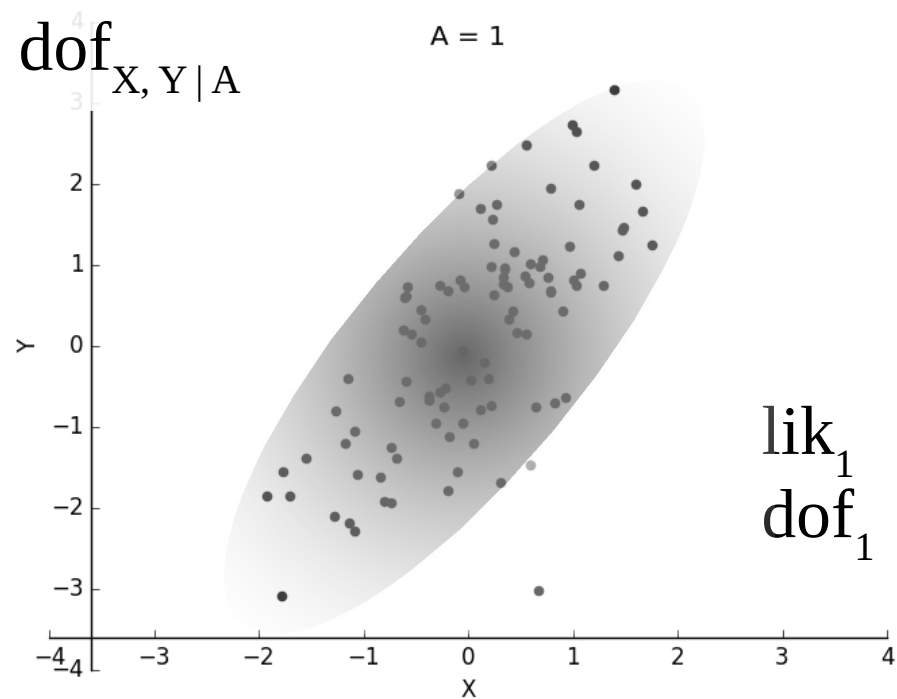
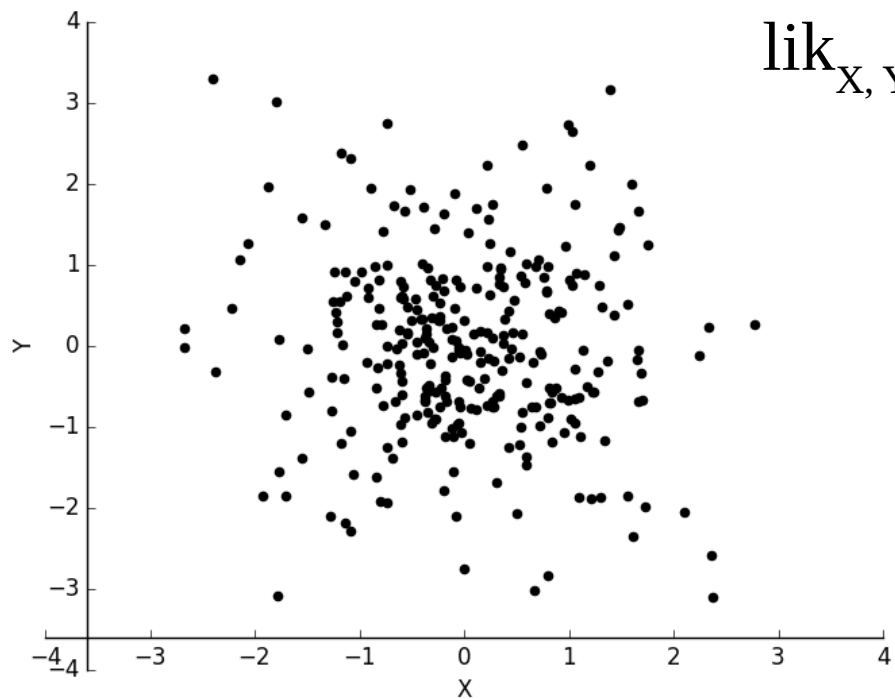


$\text{lik}_{X, Y|A}, \text{dof}_{X, Y|A}$

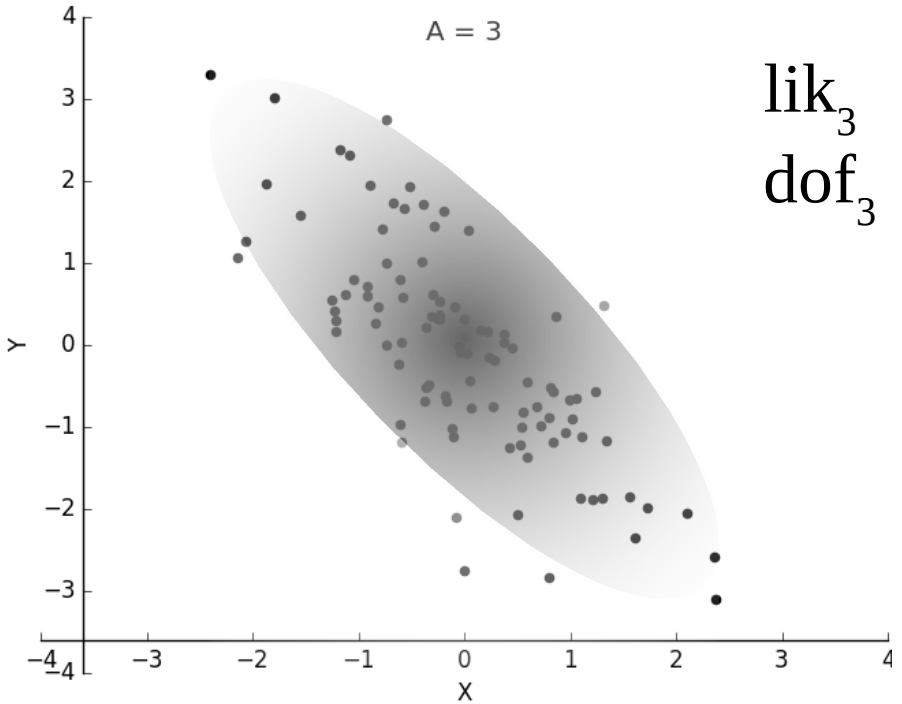
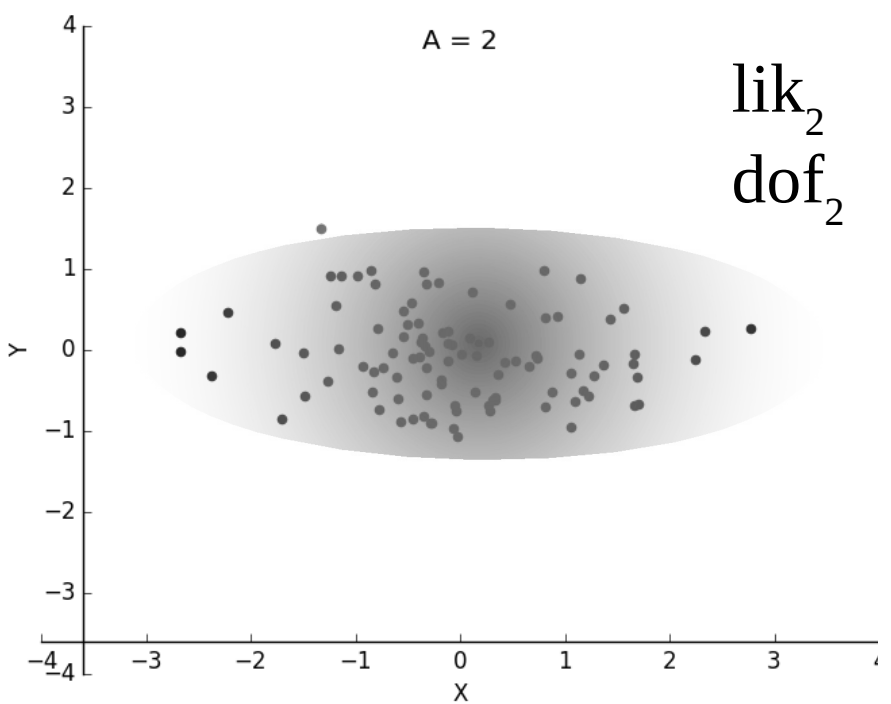
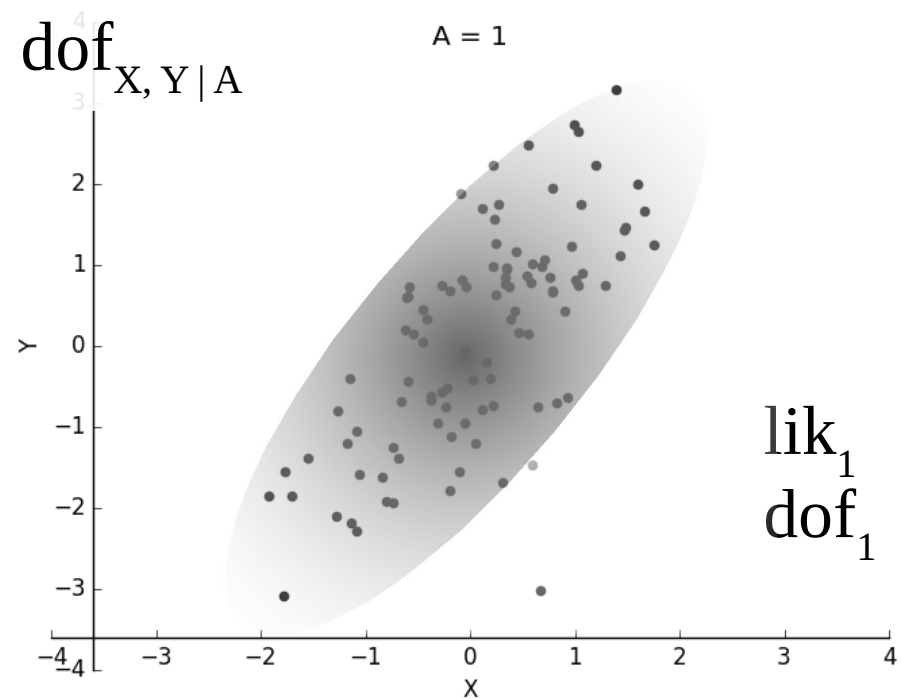
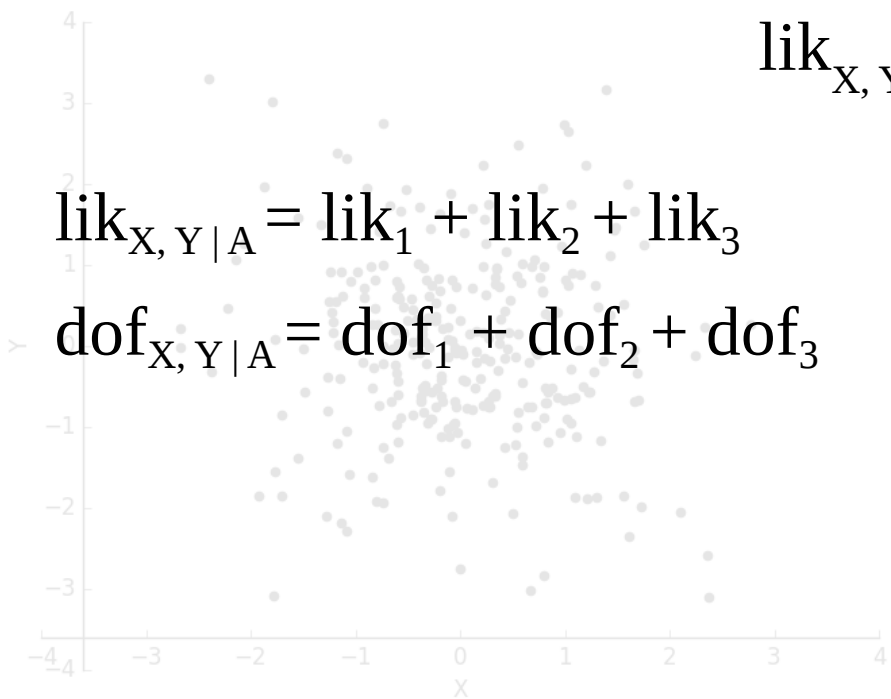


lik<sub>X, Y | A</sub>, dof<sub>X, Y | A</sub>

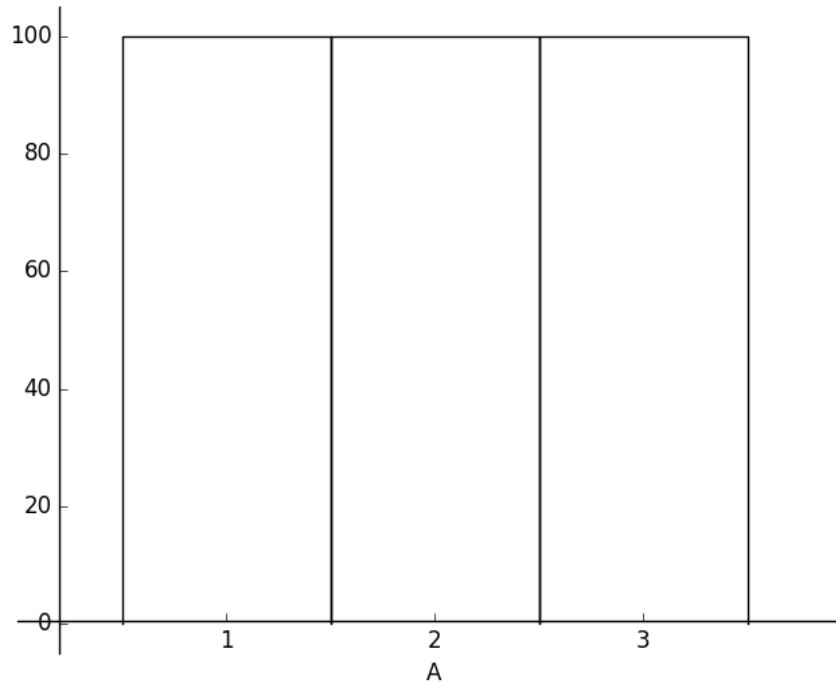




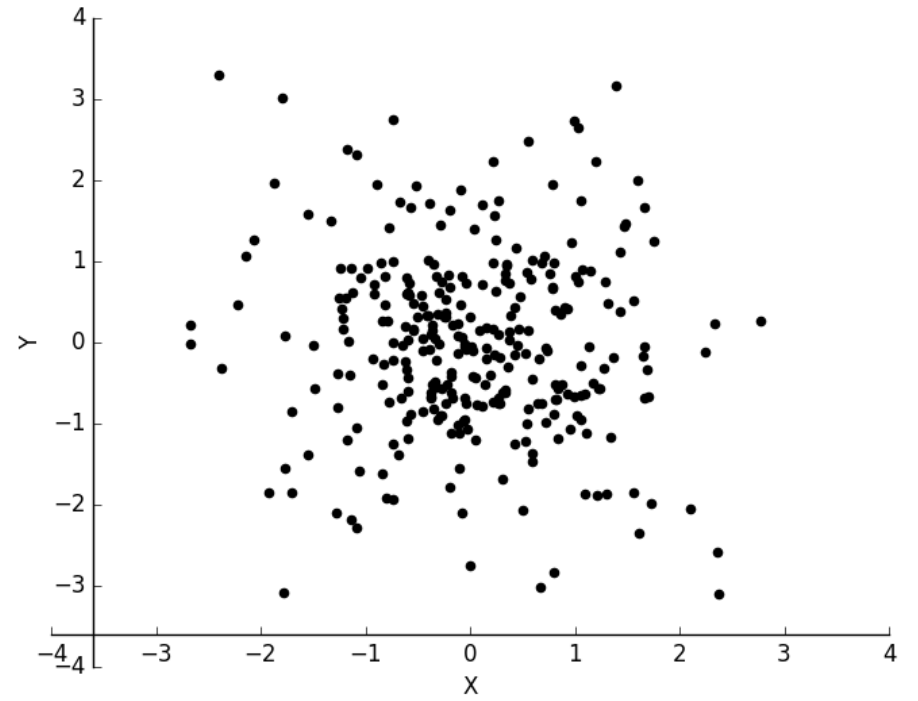




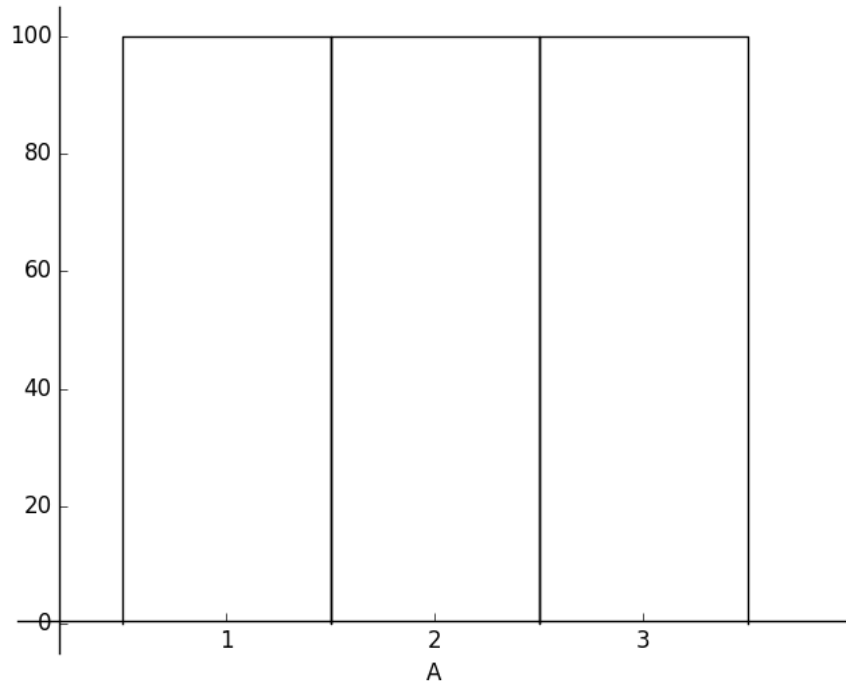
$\text{lik}_A, \text{dof}_A$



$\text{lik}_{X,Y}, \text{dof}_{X,Y}$

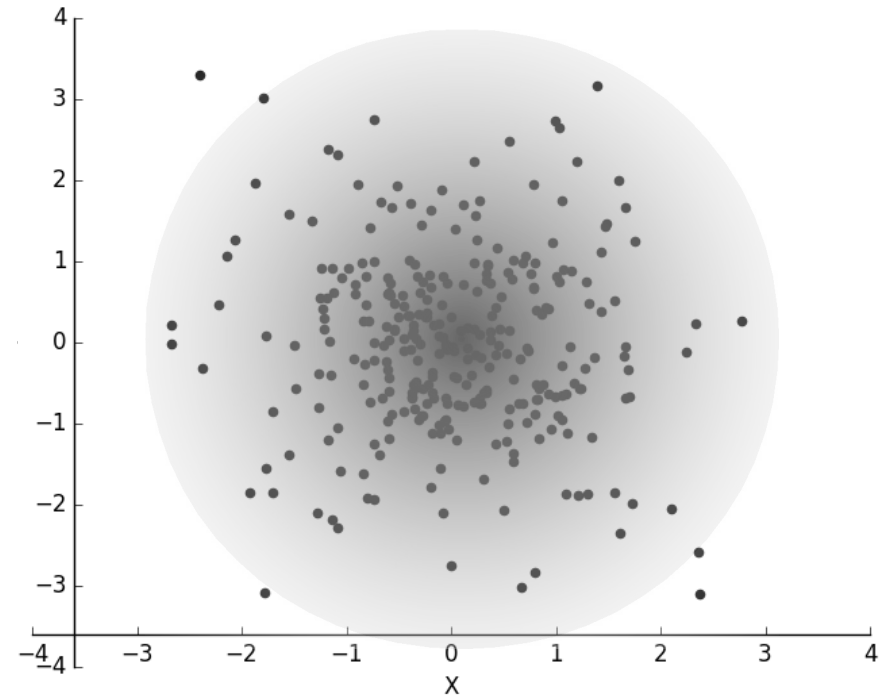


$\text{lik}_A, \text{dof}_A$



$\text{lik}_A$   
 $\text{dof}_A$

$\text{lik}_{X,Y}, \text{dof}_{X,Y}$



$\text{lik}_{X,Y}$   
 $\text{dof}_{X,Y}$

# Modeling a Discrete Child

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$\text{lik}_A$ ,  $\text{dof}_A$

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# Outline

- Bayesian Information Criterion (BIC)
- Mixed Variable Polynomial (MVP) score
- Conditional Gaussian (CG) score
- **Adaptations**
- Simulations and empirical results

# Adaptations

- Binomial Structure Prior
  - Treat the addition of each parent as an independent random trial
  - Model the prior probability of each parent-child model using a Binomial distribution
- Discretization Heuristic
  - Discretize continuous parents of discrete children in order to use multinomial scoring



# Outline

- Bayesian Information Criterion (BIC)
- Mixed Variable Polynomial (MVP) score
- Conditional Gaussian (CG) score
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- **Simulations and empirical results**

# Conditional Gaussian Simulation

- Randomly generate a set of variables and edges

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Note: For all simulation we simulate discrete-continuous at a 50-50 split where discrete variables have a random number of categories between 2 and 5

# Non-linear Simulation

- Randomly generate a set of variables and edges
- Specify a causal ordering over the variables
- In causal order, simulate one variable at a time
  - Use multinomial relationships with discretized continuous parents for discrete children
  - Use partitioned polynomial regression with Gaussian noise for continuous children

Note: For all simulation we simulate discrete-continuous at a 50-50 split where discrete variables have a random number of categories between 2 and 5



# Algorithms

**CG** – Conditional Gaussian

**CG d** – Conditional Gaussian w/ Discretization Heuristic

**MVP 1** – Mixed Variable Polynomial w/ linear basis

**MVP log n** – Mixed Variable Polynomial w/ polynomial basis

**LR 1** – Logistic Regression w/ linear basis

**LR log n** – Logistic Regression w/ polynomial basis

# Statistics

**AP** – Adjacency Precision

correctly predicted adjacent / predicted adjacent

**AR** – Adjacency Recall

correctly predicted adjacent / true adjacent

**AHP** – Arrowhead Precision

correctly predicted arrowhead / predicted arrowhead

**AHR** – Arrowhead Recall

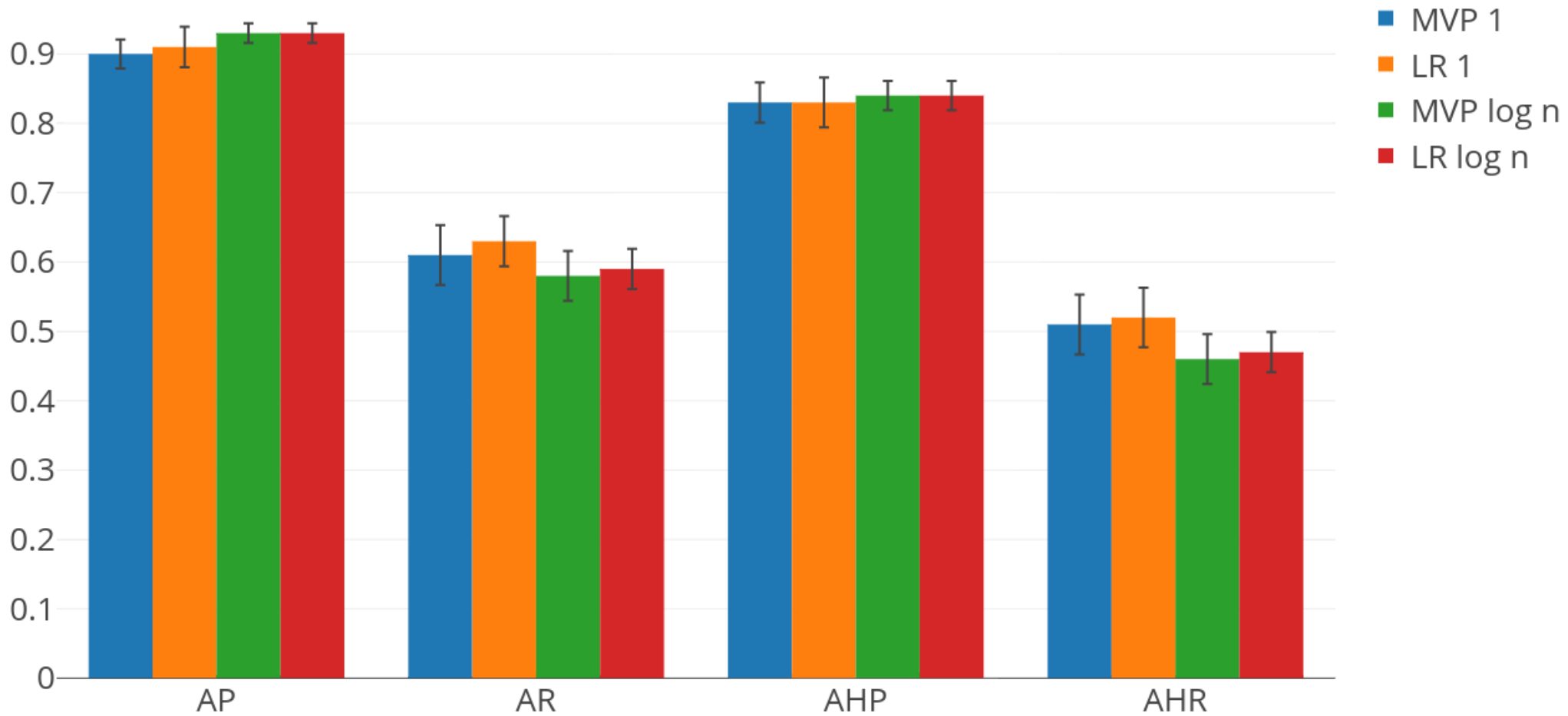
correctly predicted arrowhead / true arrowhead

**T (s)** – Computation time (in seconds)

All statistics are averaged over 10 runs on networks of 1000 instances

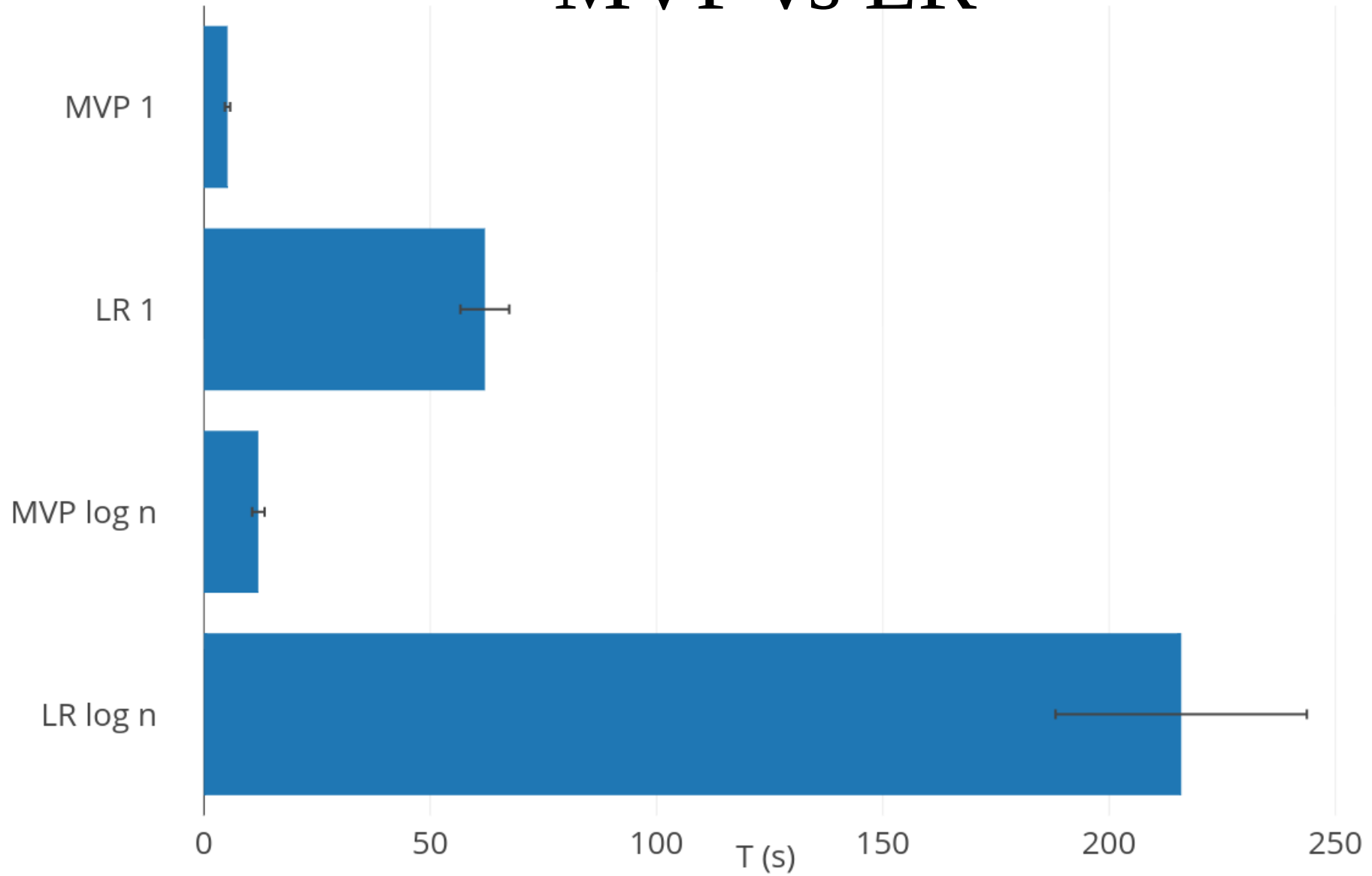
As a search fGES was used (Ramsey 2017) (Chickering 2002)<sup>82</sup>

# MVP vs LR



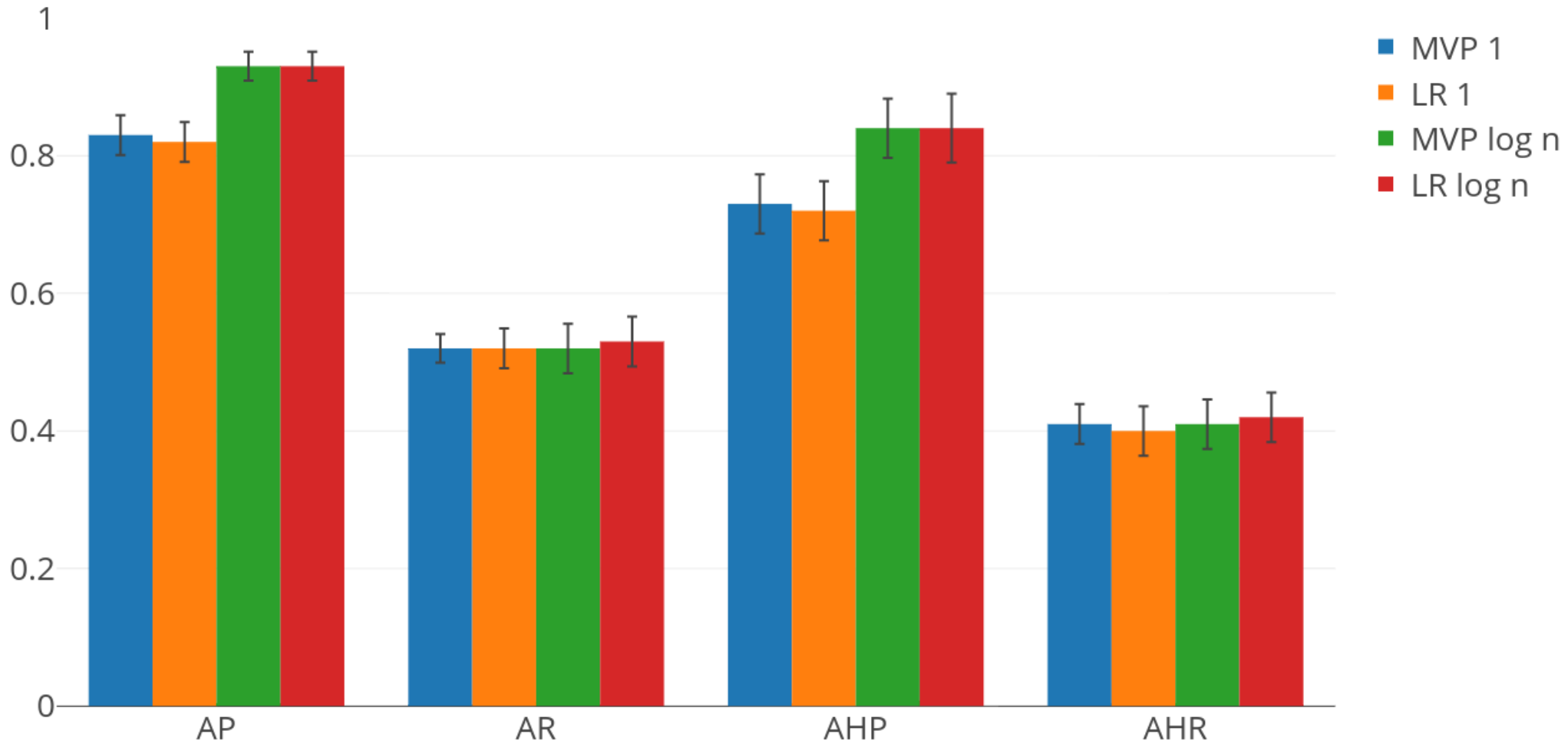
Avg Deg 4 | 100 Measured | Linear Simulation

# MVP vs LR



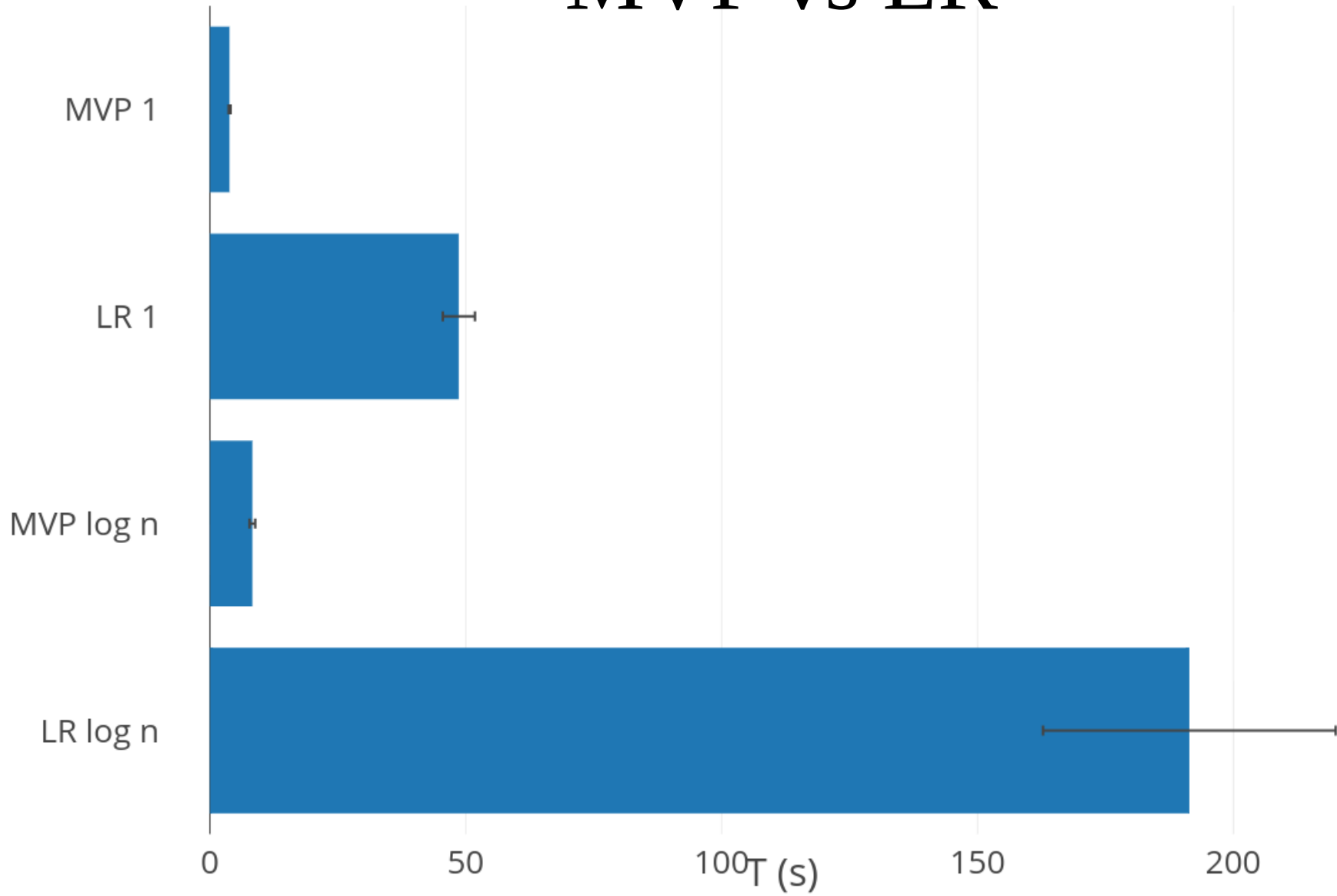
Avg Deg 4 | 100 Measured | Linear Simulation

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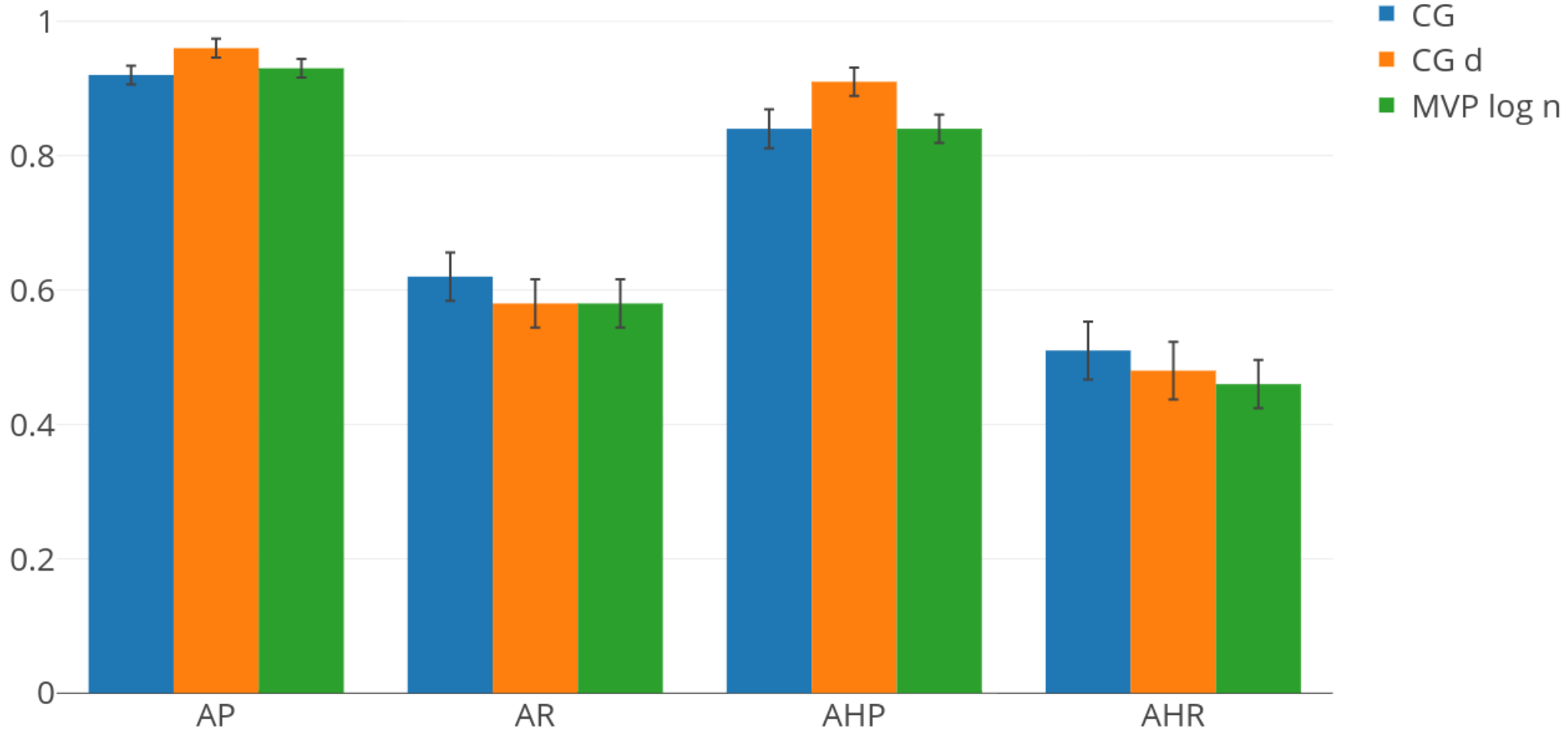
Avg Deg 4 | 100 Measured | Non-Linear Simulation

# MVP vs LR



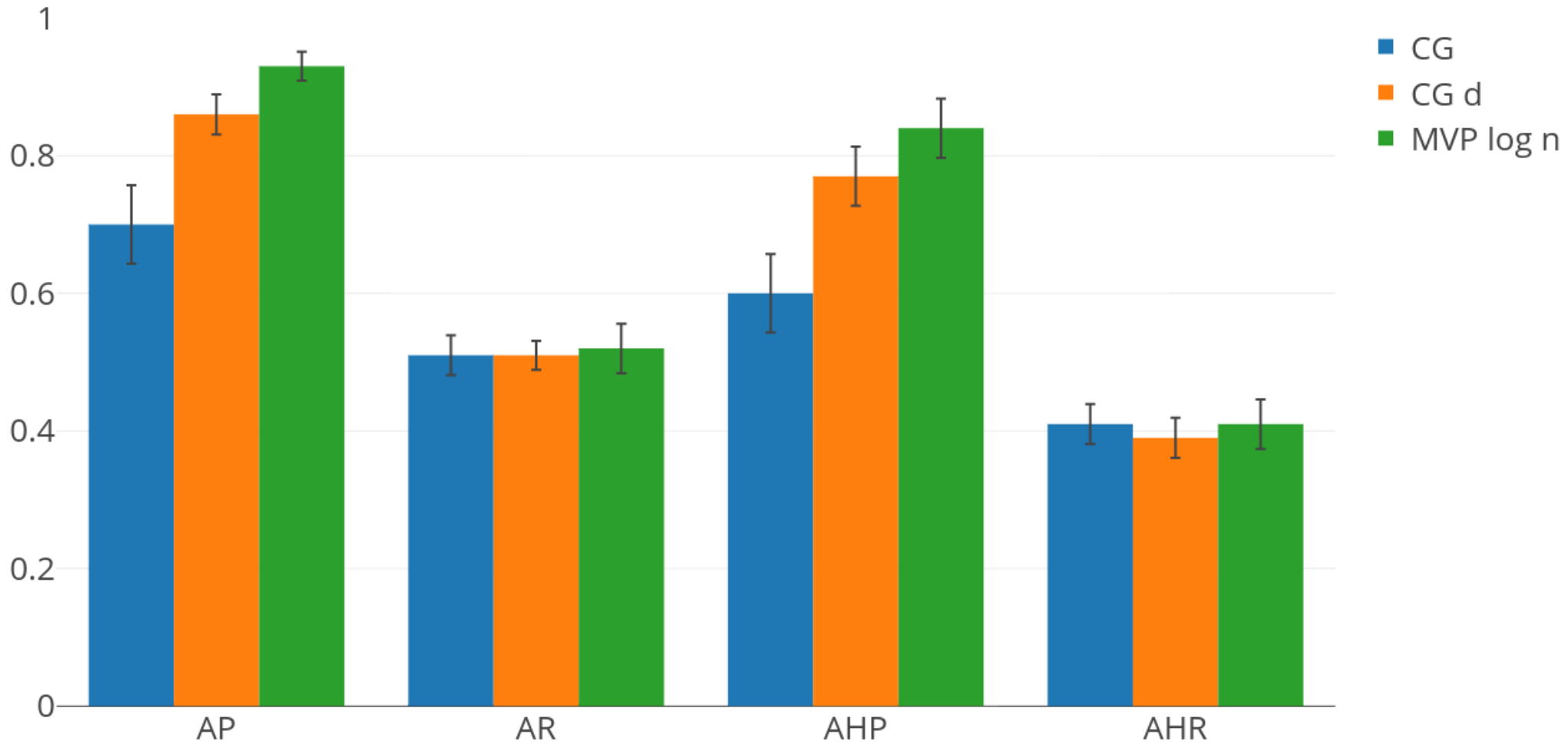
Avg Deg 4 | 100 Measured | Non-Linear Simulation

# MVP vs CG



Avg Deg 4 | 100 Measured | Linear Simulation

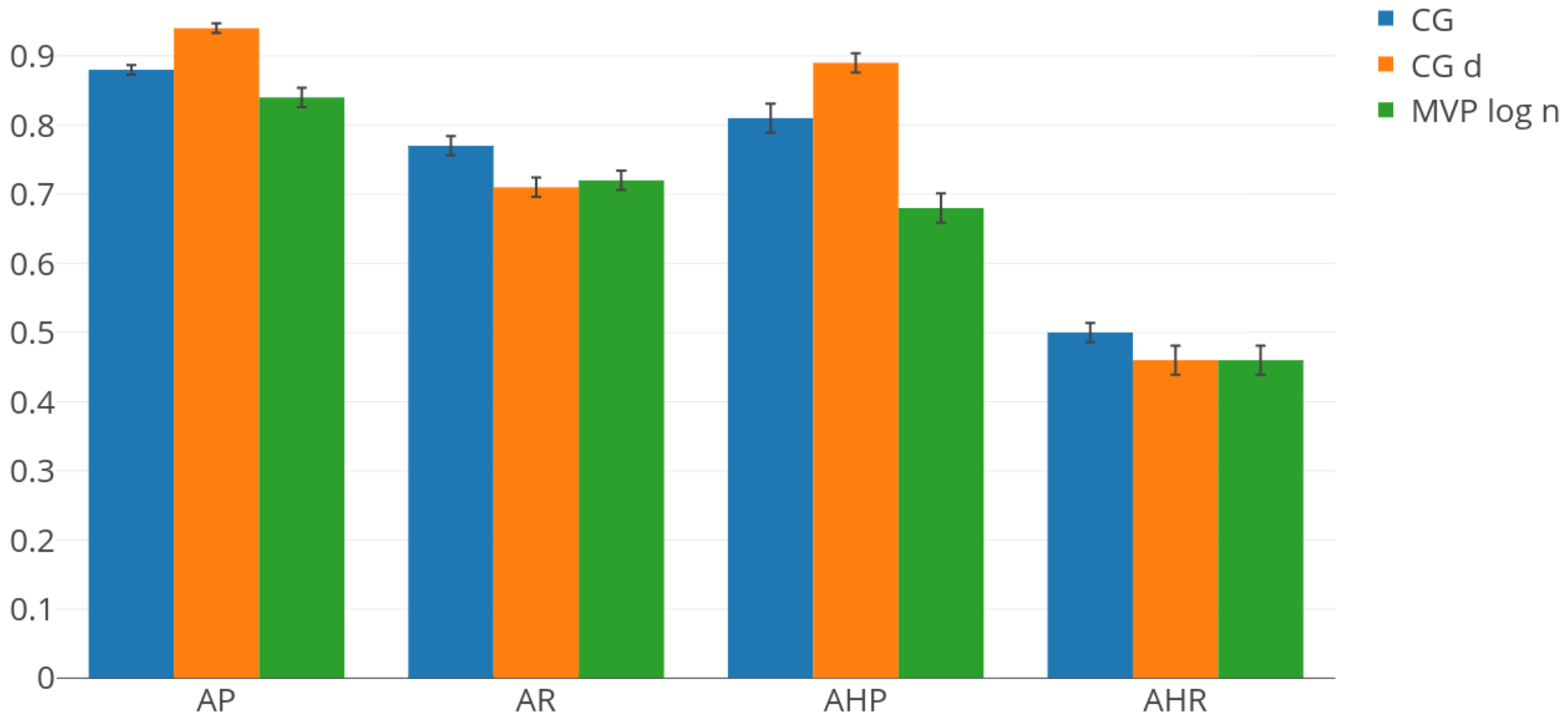
# MVP vs CG



Avg Deg 4 | 100 Measured | Non-Linear Simulation

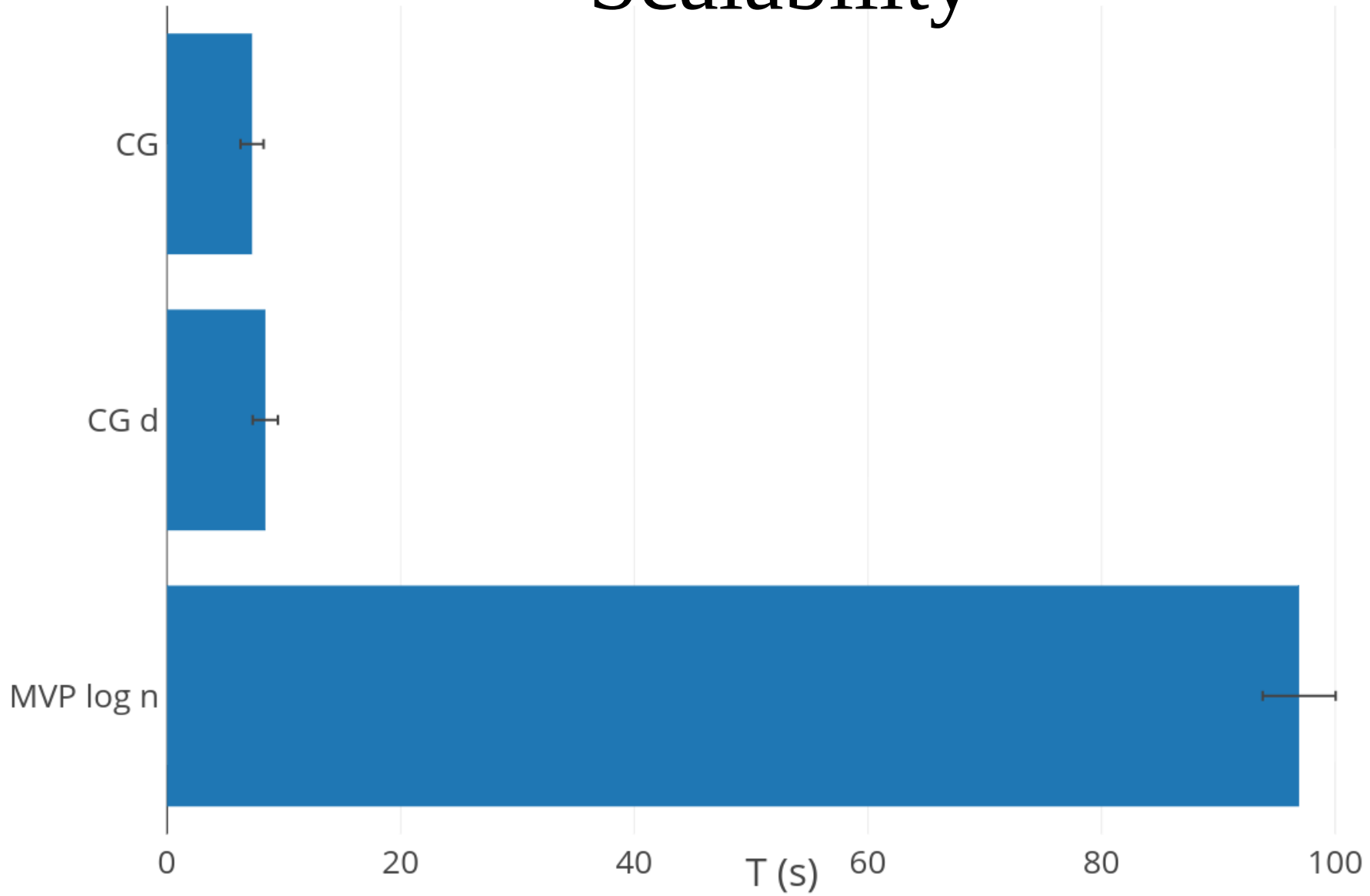


# Scalability



Avg Deg 2 | 500 Measured | Linear Simulation

# Scalability



Avg Deg 2 | 500 Measured | Linear Simulation

# Conclusions

- We present two novel scoring methods for learning BNs in the presence of both continuous and discrete variables
  - Mixed Variable Polynomial (MVP)
    - Similar performance to LR but 10-20 times faster
    - Allows for a more general class of relationship
  - Conditional Gaussian (CG)
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    - Allows for a more general class of relationship
  - Conditional Gaussian (CG)
    - Quick and effective
- Both scores perform well on simulated data (linear and non-linear) and scale to networks of at least 500 variables

# Thank You

All presented methods are available  
on Tetrad

<https://github.com/cmu-phil/tetrad>